### **Oriental motor**

Standard AC Motor
Three-Phase High-Efficiency
Induction Motor

### **KIIS** Series

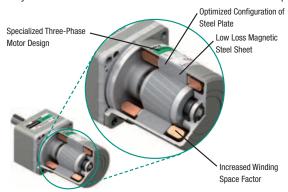
Terminal Box Type
Right-Angle Hypoid Gear JH Gearhead
Stainless Steel Shaft / IP66
30 W (1/25 HP) / 40 W (1/19 HP) / 100 W (1/8 HP)



### High Efficiency Three-Phase Motors through Optimal Design

### High Efficiency at a Maximum of 74%

Specialized components and an optimal magnetic design are used to make high efficiency three-phase motors with a maximum efficiency of 74%. Motors are fanless with increased motor torque.



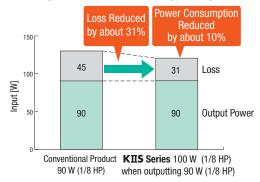
#### Comparison of Max. Efficiency (Reference values)

	30 W	60 W	100 W
<b>KIIS</b> Series	63.8%	69.8%	74.1%
Conventional Product	53.9% (25 W)	60.5%	64.7% (90 W)

Rated Output Power at 60 Hz

### Power Consumption Reduced by up to 10%

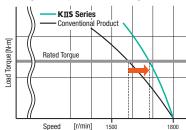
Compared to a conventional 90 W (1/8 HP) motor under the same conditions, power consumption is reduced by a maximum of about 10%, contributing to the equipment's energy savings.



### High Performance

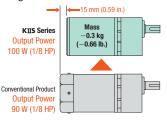
Characteristics have been improved through pursuit of the specifications required for the three-phase motor and a review of the design to create a high-performance motor with little speed reduction even with a large load.

Changes in Speed according to Load



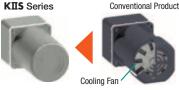
#### Increased Motor Output Power

Output power of 100 W (1/8 HP) in a 90 mm (3.54 in.) frame size is achieved through increased efficiency. An overall length 15 mm (0.59 in.) shorter than the conventional motor contributes to equipment downsizing.



#### Fanless

With reduced loss, there is less heat generation in the motor, so the cooling fan that was incorporated into the conventional 60 W (1/12 HP) min. products is no longer included.



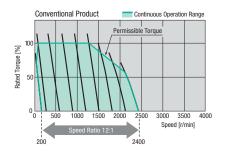
•No Dust, etc.

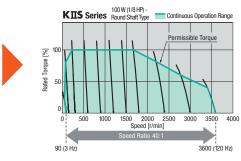
With no cooling fan, dust is not blown around.

### Best Characteristics Achieved when Combined with an Inverter

#### Wide Range of Speeds

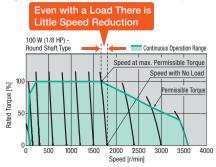
Speed can be controlled over a wide range using an inverter, from 3~120 Hz. Also, with improved characteristics, high torque can be exerted even at low speeds.





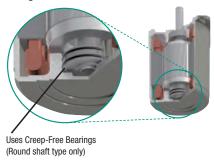
### Improved Speed Stability

Because it is a high-performance motor with little speed reduction even with a large load, stabilized speed control is possible.



### Handles High-Speed Rotation (Round shaft type)

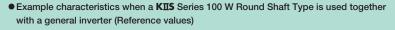
Creep-free bearings, etc. are used in the round shaft type, and components capable of handling high-speed rotation have been selected and designed for inverter control.

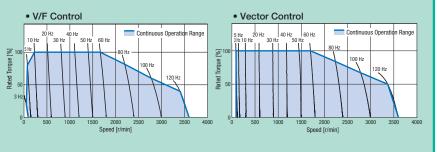


### Usage with non-Oriental Motor Inverters

"Speed – Torque Characteristics" and "Inverter Parameter Setting Values" when using a non-Oriental Motor inverter have been prepared as a reference in order to make use with other inverters easier.

For details, please see the Oriental Motor website.



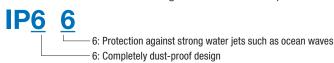


### Note

No built-in overheat protection device (thermal protector). When the output shaft is locked for any reason, use the electromagnetic switch and the inverter's electronic thermal function to prevent motor burnout.

### Motors with terminal box conforming to IP66 rating for degree of protection.

- Strengthened Seal Structure for the Motor, Gearhead and Terminal Box Components
- The IP indication that shows the watertight and dust-resistant performance is specified under IEC 60529 and IEC 60034-5.



Right-Angle Shaft Hollow Hypoid JH Gear



Parallel Shaft Gearhead GV Gear, Round Shaft Type



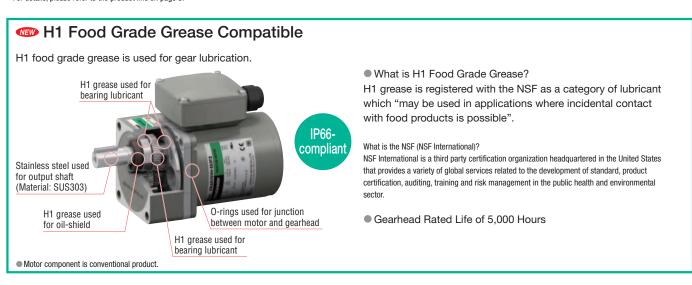
### Stainless Steel Shaft Is Included as Standard\*

Uses an output shaft made of stainless steel, which has excellent rust and corrosion resistance
 Parallel key and installation screws also use stainless steel.



\*Some products do not have stainless steel shafts.

For details, please refer to the product line on page 5.



### Utilizes a Gearhead that Excels in Both Torque and Strength

### Right-Angle Shaft Hollow Hypoid JH Gear



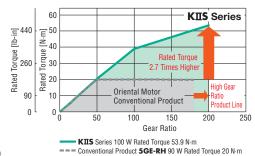
Uses high-strength hypoid gears Greatly increased torque and reduced noise compared to conventional products. Both the radial load and the axial load have been significantly increased, contributing to decreased equipment size and improved reliability.

# Permissible Radial Load Permissible Axial Load Nutrout Power 100 W (1/8 HP)

Output Power 100 W (1/8 HP)

Permissible Radial Load  $\,$  1291 N (290 lbs.) 10 mm (0.39 in.) from Installation Surface

Permissible Axial Load 343 N (77 lbs.)



Parallel Shaft Gearhead GV Gear



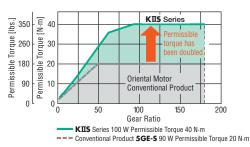
By increasing the size of the output shaft bearing and adopting carburized gears, the torque, permissible radial load and permissible axial load have all been increased compared to a conventional product.



Output Power 100 W (1/8 HP)

Permissible Radial Load 500 N (112 lbs.) (10 mm from the end of the output shaft)

Permissible Axial Load 150 N (33 lbs.)



### Pre-Assembled Motor and Gearhead Combinations (Right-Angle Shaft Hollow Hypoid **JH** Gear, Parallel Shaft Gearhead **GV** Gear)

Motor and gearhead are delivered pre-assembled. This reduces assembly time and allows for immediate installation.



Gearhead can be detached.

The motor position can be rotated in 90° increments and the lead wire draw direction can also be changed. By purchasing just the gearhead, the gear ratio can be changed, or it can be replaced during maintenance.



### **■KII\$** Series Product Line

### Induction Motor Right-Angle Shaft Hollow Hypoid JH Gear

				Frame Size (mn	□90		
Voltage [VAC]	Туре	External View, Output Shaft Material	□80				
			30 W (1/25 HP)	40 W (1/19 HP)	60 W (1/12 HP)	100 W (1/8 HP)	
Three-Phase 220/230/240	Terminal Box Type	Stainless Shaft	•	•	_	*	

<sup>\*100</sup> W (1/8 HP) not available in three-phase 240 VAC.

### Induction Motor Parallel Shaft Gearhead GV Gear, Round Type Stainless Shaft

			Frame Size (mm), Output Power			
Voltage [VAC]	Туре	External View, Output Shaft Material	□80 □90			
			30 W (1/25 HP)	40 W (1/19 HP)	60 W (1/12 HP)	100 W (1/8 HP)
Three-Phase 220/230/240	Terminal Box Type	NEW Stainless Shaft	•	•	•	•
Three-Phase 220/230/240	Terminal Box Type H1 Food Grade Grease Compatible	Stainless Shaft	_	_	•	•

Terminal box type with stainless shaft has been revised with a different motor structure.

### Gearhead Gear Ratio

Out	put	Gear Ratio
30 W (1	/25 HP)	5~360
40 W (1	/19 HP)	5~300
60 W (1	/12 HP)	5~300
100 W (	1/8 HP)	5~180
Speed*	50 Hz	300~4.1
Speed	60 Hz	360~5
Configuration	on Example	

<sup>\*</sup>The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

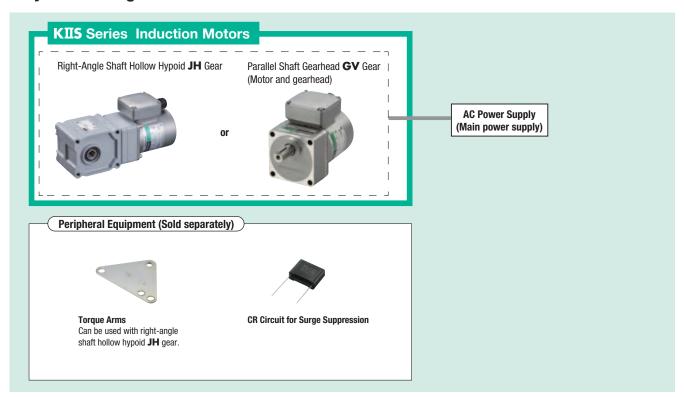
### Induction Motor Parallel Shaft Gearhead GV Gear Round Shaft Type

		• • • • • • • • • • • • • • • • • • • •					
			Frame Size (mm), Output Power				
Voltage [VAC]	Туре	External View, Output Shaft Material	nal View, Output Shaft Material 80 90				
			30 W (1/25 HP)	40 W (1/19 HP)	60 W (1/12 HP)	100 W (1/8 HP)	
	Terminal Box Type	Iron Shaft	_	_	•	•	
Three-Phase 220/230	Lead Wire	Iron Shaft	_	_	•	•	

### Motor with an Electromagnetic Brake Parallel Shaft Gearhead GV Gear Round Shaft Type

				Frame Size (mn	n), Output Power		
Voltage [VAC]	Туре	External View, Output Shaft Material	□80		m), Output Power		
			30 W (1/25 HP)	40 W (1/19 HP)	60 W (1/12 HP)	100 W (1/8 HP)	
Three-Phase 220/230	Terminal Box Type	Iron Shaft	_	_	•	•	
	Cables	lron Shaft	_	_	•	•	

### System Configuration



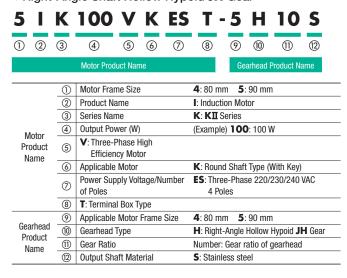
### ●Example of System Configuration

Induction Motor Right-Angle		Sold Se	parately
Shaft Hollow Hypoid <b>JH</b> Gear	+	Torque Arms	CR Circuit for Surge Suppression
5IK100VKJST-5H10S		TAF2S-15-NS	EPCR1201-2
\$472.00		\$25.00	\$5.00

• The system configuration shown above is an example. Other combinations are also available.

### Product Number

Right-Angle Shaft Hollow Hypoid JH Gear



● Parallel Shaft Gearhead GV Gear

_	_	 100	_	 _		 _	
		4					

Round Shaft Type

_	1 1/	100	1/		•	FC	2	-	•
<u> </u>	IK	100	V	A	<u> </u>	- ES	3	I Z	_
1	2 3	4	⑤	10	11)	6	⑦ (	8 9	)
1	Motor Fram	ne Size		<b>4</b> : 80	mm <b>5</b> :	90 mm			
2	Product Na	me		I: Indu	ction Mot	or			
3	Series Nam	ne .		K: KI	<b>I</b> Series				
4	Output Pov	ver (W)		(Exam	ple) <b>100</b>	: 100 W			
(5)	V: Three-P	V: Three-Phase High Efficiency Motor							
6	Power Supply Voltage/Number ES: Three-Phase 220/230/240 VAC 4 Poles of Poles								
7	Identification	on Symbol							
8	M: With Po	wer Off Acti	vated Ty	/pe Elect	romagnet	ic Brake			
9		al Box Type d Wire Type o	or Cable	Туре					
10	Gear Ratio and Shaft Type  Number: Gear ratio of gearhead  A: Round Shaft Type								
11)	Output Shat	ft Material		<b>S</b> : Stai None:	nless stee Iron	l			
12	F: Compatil	ole with H1 F	ood Gra	ade Grea	se				

### **Induction Motors**

### 30 W (1/25 HP)

**□80 mm (□3.15 in.)** 

**KIIS** Series Right-Angle Hollow Shaft Hypoid **JH** Gear Stainless Shaft



Terminal Box Type

### Specifications - Continuous Rating

c**™**us ((€

Product Name Terminal Box Type	Output W (HP)	Voltage VAC	Frequency Hz	Current A
		Three-Phase	0.23	
		220	60	0.20
4IK30VKEST-4H□S	30	Three-Phase	50	0.24
41K30 VKE31-411_3	(1/25)	230	60	0.20
		Three-Phase	50	0.25
		240	60	0.20

Gear Ratio		10	15	20	30	50	100	200
Cnood [r/min]	50 Hz	150	100	75	50	30	15	7.5
Speed [r/min]	60 Hz	180	120	90	60	36	18	9
Rated Torque	50 Hz	1.13 (10)	1.69 (14.9)	2.3 (20)	3.4 (30)	5.6 (49)	11.3 (100)	20.6 (182)
Upper Level: N·m Lower Level: lb-in	60 Hz	0.94 (8.3)	1.4 (12.3)	1.87 (16.5)	2.8 (24)	4.7 (41)	9.4 (83)	18.7 (165)
Starting Torque Upper Level: N·m Lower Level: Ib-in	50 Hz	1.35 (11.9)	2.0 (17.7)	2.7 (23)	4.1 (36)	6.8 (60)	13.5 (119)	20.6 (182)
	60 Hz	0.9 (7.9)	1.35 (11.9)	1.8 (15.9)	2.7 (23)	4.5 (39)	9.0 (79)	18.0 (159)
Permissible Load Inertia J Upper Level: ×10 <sup>-4</sup> kg·m <sup>2</sup>		100 (550)	225 (1230)	400 (2200)	900 (4900)	2500 (13700)	10000 (55000)	40000 (220000)
Lower Level: x10 'kg-III-	Instantaneous Stop	33.3 (182)	75 (410)	133 (730)	300 (1640)	833 (4600)	3333 (18200)	13333 (73000)
Permissible Radial Load Upper Level: N Lower Level: lb.*	10 mm (0.39 in.) from Installation Surface	311 (69)	400 (90)	488 (109)	622 (139)	799 (179)	888 (199)	978 (220)
	20 mm (0.79 in.) from Installation Surface	265 (59)	341 (76)	417 (93)	531 (119)	682 (153)	758 (170)	836 (188)
Permissible Axial Load Upper Level: N Lower Level: lb.		88 (19.8)	108 (24)	137 (30)	177 (39)	226 (50)	245 (55)	275 (61)

The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

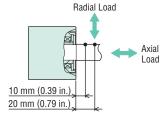
The actual speed is up to 20% less, depending on the load.

When there is an overload or the output shaft is locked, use the electromagnetic switch and the inverter's electronic thermal function to prevent motor burnout.

Use an inverter setting frequency of 100 Hz or less when driving in combination with the inverter.
 Note

Do not perform instantaneous bi-directional operations.

### $\Diamond$ Load Position



Distance from Installation Surface

### Product Line

### Terminal Box Type

Product Name	Gear Ratio	List Price
	10, 15, 20	402.00
4IK30VKEST-4H□S	30, 50, 100	413.00
	200	423.00

### Included

Installation Screws	Parallel Key (Stainless)	Safety Cover	Operating Manual
1 set	1 piece	1 piece	1 copy

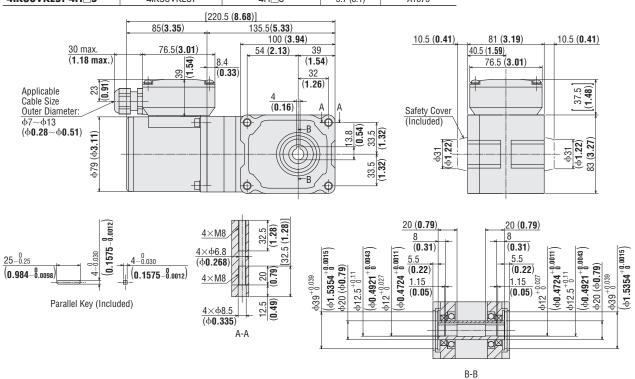
lacktriangle A number indicating the gear ratio is entered where the box  $\Box$  is located within the product name.

No built-in overheat protection device (thermal protector).

### Dimensions Unit: mm (in.)

- Installation screws are included.
- The terminal box cable outlet can be rotated and affixed in 4 possible directions.
- lacktriangle A number indicating the gear ratio is entered where the box  $\Box$  is located within the product name.

# Product Name Motor Product Name Gearhead Product Name Mass kg (lb.) 2D CAD 4IK30VKEST-4H□S 4IK30VKEST 4H□S 3.7 (8.1) A1673



### **Induction Motors**

### 40 W (1/19 HP)

□90 mm (□3.54 in.)

**KIIS** Series Right-Angle Hollow Shaft Hypoid JH Gear Stainless Shaft



### Specifications - Continuous Rating

c**¶**°us (€

Product Name Terminal Box Type	Output W (HP)	Voltage VAC	Frequency Hz	Current A
		Three-Phase	50	0.27
5IK40VKEST-5H□S	40 (1/19)	220	60	0.24
		Three-Phase	50	0.29
		230	60	0.24
		Three-Phase	50	0.30
		240	60	0.25

Gear Ratio		10	15	20	30	50	100	200
Cacad [r/min]	50 Hz	150	100	75	50	30	15	7.5
Speed [r/min]	60 Hz	180	120	90	60	36	18	9
Rated Torque	50 Hz	1.38	2.1	2.8	4.1	6.9	15.1	30.3
Upper Level: N·m		(12.2)	(18.5)	(24)	(36)	(61)	(133)	(260)
Lower Level: Ib-in	60 Hz	1.15 (10.1)	1.73 (15.3)	2.3 (20)	3.5 (30)	5.8 (51)	12.7 (112)	25.3 (220)
Starting Torque	50 Hz	2.0 (17.7)	3.0 (26)	4.0 (35)	6.0 (53)	10.0 (88)	22.0 (194)	44.0 (380)
Upper Level: N·m	60 Hz	1.3	1.95	2.6	3.9	6.5	14.3	28.6
Lower Level: Ib-in		(11.5)	(17.2)	(23)	(34)	(57)	(126)	(250)
Permissible Load Inertia J		200	450	800	1800	5000	20000	80000
Upper Level: ×10 <sup>-4</sup> kg·m <sup>2</sup>		(1090)	(2500)	(4400)	(9800)	(27000)	(109000)	(440000)
Lower Level: oz-in <sup>2</sup>	Instantaneous Stop	66.7 (360)	150 (820)	267 (1460)	600 (3300)	1667 (9100)	6667 (36000)	26667 (146000)
Permissible Radial Load	10 mm (0.39 in.) from	415	554	692	923	1112	1196	1291
	Installation Surface	(93)	(124)	(155)	(200)	(250)	(260)	(290)
Upper Level: N	20 mm (0.79 in.) from	363	484	605	806	971	1045	1127
Lower Level: lb.*	Installation Surface	(81)	(108)	(136)	(181)	(210)	(230)	(250)
Permissible Axial Load	l: lb.	108	147	186	245	294	324	343
Upper Level: N Lower Leve		(24)	(33)	(41)	(55)	(66)	(72)	(77)

The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is up to 20% less, depending on the load.

No built-in overheat protection device (thermal protector).

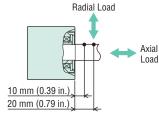
When there is an overload or the output shaft is locked, use the electromagnetic switch and the inverter's electronic thermal function to prevent motor burnout.

• Use an inverter setting frequency of 80 Hz or less (60 Hz or less with gear ratio 10) when driving in combination with the inverter.

### Note

Do not perform instantaneous bi-directional operations.

### ♦ Load Position



Distance from Installation Surface

### Product Line

### Terminal Box Type

Product Name	Gear Ratio	List Price
	10, 15, 20	457.00
5IK40VKEST-5H□S	30, 50, 100	463.00
	200	465.00

### Included

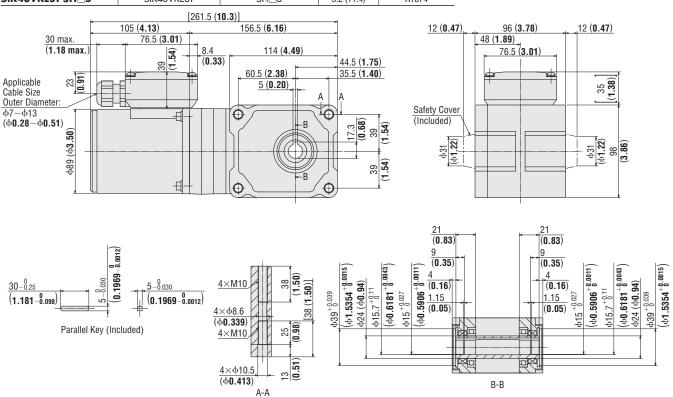
Installation Screws	Parallel Key (Stainless)	Safety Cover	Operating Manual
1 set	1 piece	1 piece	1 copy

lacktriangle A number indicating the gear ratio is entered where the box  $\Box$  is located within the product name.

### Dimensions Unit: mm (in.)

- Installation screws are included.
- The terminal box cable outlet can be rotated and affixed in 4 possible directions.
- A number indicating the gear ratio is entered where the box □ is located within the product name.

# Product Name Motor Product Name Gearhead Product Name Mass kg (lb.) 2D CAD 5IK40VKEST-5H□S 5IK40VKEST 5H□S 5.2 (11.4) A1674



### **Induction Motors**

### 100 W (1/8 HP)

□90 mm (□3.54 in.)

**KIIS** Series Right-Angle Hollow Shaft Hypoid JH Gear Stainless Shaft



### Specifications - Continuous Rating

**™** su (€

Product Name Terminal Box Type	Output W (HP)	Voltage VAC	Frequency Hz	Current A
5IK100VKEST-5H□S	100 (1/8)	Three-Phase	50	0.49
		220	60	0.46
		Three-Phase	50	0.49
		230	60	0.45

Gear Ratio		10	15	20	30	50	100	200
Cnood [r/min]	50 Hz	150	100	75	50	30	15	7.5
Speed [r/min]	60 Hz	180	120	90	60	36	18	9
Rated Torque Upper Level: N·m	50 Hz	4.1 (36)	6.1 (53)	8.3 (73)	12.7 (112)	20.6 (182)	39.2 (340)	53.9 (470)
Lower Level: Ib-in	60 Hz	4.1 (36)	6.1 (53)	8.2 (72)	12.4 (109)	20.6 (182)	39.2 (340)	53.9 (470)
Starting Torque Upper Level: N·m	50 Hz	4.1	6.1	8.3	12.7	20.6	39.2	53.9
Lower Level: Ib-in	60 Hz	(36)	(53)	(73)	(112)	(182)	(340)	(470)
Permissible Load Inertia J Upper Level: ×10-4kg·m <sup>2</sup>		200 (1090)	450 (2500)	800 (4400)	1800 (9800)	5000 (27000)	20000 (109000)	80000 (440000)
Lower Level: oz-in <sup>2</sup>	Instantaneous Stop	66.7 (360)	150 (820)	267 (1460)	600 (3300)	1667 (9100)	6667 (36000)	26667 (146000)
Permissible Radial Load	10 mm (0.39 in.) from Installation Surface	415 (93)	554 (124)	692 (155)	923 (200)	1112 (250)	1196 (260)	1291 (290)
Upper Level: N Lower Level: lb.*	20 mm (0.79 in.) from Installation Surface	363 (81)	484 (108)	605 (136)	806 (181)	971 (210)	1045 (230)	1127 (250)
Permissible Axial Load Upper Level: N Lower Leve	ıl: lb.	108 (24)	147 (33)	186 (41)	245 (55)	294 (66)	324 (72)	343 (77)

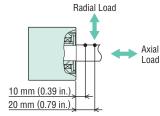
The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

When there is an overload or the output shaft is locked, use the electromagnetic switch and the inverter's electronic thermal function to prevent motor burnout.

Use an inverter setting frequency of 120 Hz or less when driving in combination with the inverter.
 Note

Do not perform instantaneous bi-directional operations.

### ♦ Load Position



Distance from Installation Surface

### Product Line

### Terminal Box Type

Product Name	Gear Ratio	List Price
	10, 15, 20	472.00
5IK100VKEST-5H□S	30, 50, 100	478.00
	200	480.00

### Included

Installation	Parallel Key	Safety Cover	Operating	
Screws	(Stainless)		Manual	
1 set	1 piece	1 piece	1 сору	

 $\blacksquare$  A number indicating the gear ratio is entered where the box  $\square$  is located within the product name.

The actual speed is up to 20% less, depending on the load.

No built-in overheat protection device (thermal protector).

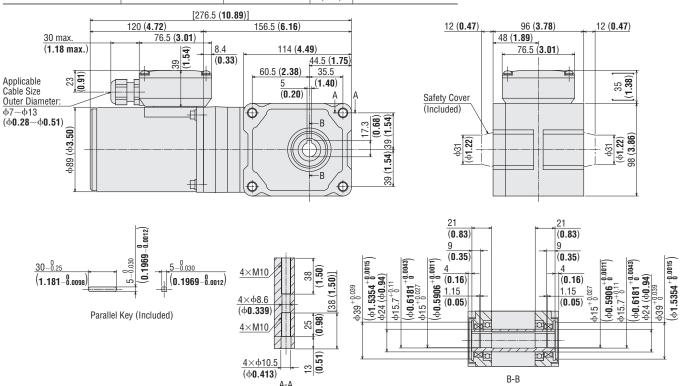
### **Dimensions** Unit: (mm)

- Installation screws are included.
- The terminal box cable outlet can be rotated and affixed in 4 possible directions.
- lacktriangle A number indicating the gear ratio is entered where the box  $\Box$  is located within the product name.

### Terminal Box Type

### 2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Mass kg (lb.)	2D CAD
5IK100VKEST-5H□S	5IK100VKEST	5H□S	6.0 (13.2)	A1675



### ■General Specifications

### Right-Angle Shaft Hollow Hypoid JH Gear

Item	Specifications
Insulation Resistance	$100 \text{ M}\Omega$ or more when a 500 VDC megger is applied between the motor windings and the case after continuous operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5 kVAC at 50 Hz or 60 Hz applied between the motor windings and the case for 1 minute after continuous operation under normal ambient temperature and humidity.
Temperature Rise	Temperature rise of windings is 80°C (176°F) or less measured by the resistance change method after rated load continuous operation under normal ambient temperature and humidity.
Thermal Class	130 (B)
Operating Ambient Temperature	$0\sim +40^{\circ}C$ (+32 $\sim +104^{\circ}F$ ) (Non-freezing)
Operating Ambient Humidity	85% or less (Non-condensing)
Degree of Protection	IP66*2

Note

No built-in overheat protection device (thermal protector).

When there is an overload or the output shaft is locked, use the electromagnetic switch and the inverter's electronic thermal function to prevent motor burnout.

### Parallel Shaft Gearhead GV Gear, Round Shaft Type

Item	Specifications
Insulation Resistance	$100~\mathrm{M}\Omega$ or more when a 500 VDC megger is applied between the motor windings and the case after continuous operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5 kVAC at 50 Hz or 60 Hz applied between the motor windings and the case for 1 minute after continuous operation under normal ambient temperature and humidity.
Temperature Rise	A gearhead or equivalent heat sink*1 is connected to the motor, and the winding temperature rise is measured at 80°C (176°F) or less using the resistance change method after 30 minutes continuous operation with no load under normal ambient temperature and humidity.
Thermal Class	130 (B)
Operating Ambient Temperature	$-10^{\circ}$ $\sim$ $+40^{\circ}$ C (+32 $\sim$ +104°F) (Non-freezing)
Operating Ambient Humidity	85% or less (Non-condensing)
Degree of Protection	Terminal Box Type: IP66 *2 (Excluding the installation surface of the round shaft type.) Lead Wire Type: IP20 Cable Type: IP40

#### \*1 Heat sink size (Material: Aluminum)

Motor Type	Size: mm (in.)	Thickness: mm (in.)	
30 W Type	135×135 (5.31×5.31)		
40 W Type	165×165 (6.50×6.50)	E (0.20)	
60 W Type 100 W Type	200×200 (7.87×7.87)	5 (0.20)	

\*2 Materials and Surface Treatments

Terminal Box Type: IP66

	Туре	Output	Materials	Surface Treatment
Stainless Shaft	Right-Angle Shaft Hollow Hypoid <b>JH</b> Gear	30 W (1/25 HP), 40 W (1/19 HP), 100 W (1/8 HP)	Motor case, gear case and terminal box: Aluminum Output shaft: Stainless steel Screws: Stainless steel (externally facing screws only)	Motor case, gear case and terminal box: Painted (excluding installation surface)
	Parallel Shaft Gearheads, <b>GV</b> Gear, Round Shaft	30 W (1/25 HP), 40 W (1/19 HP), 60 W (1/12 HP), 100 W (1/8 HP)	Motor case, gear case and terminal box: Aluminum Output shaft: SUS303 Screws: Stainless steel (externally facing screws only)	Motor case, gear case and terminal box: Painted (excluding installation surface)
Type Output		Materials	Surface Treatment	
Parallel Shaft Gearheads <b>GV</b> Gear, Round Shaft		60 W (1/12 HP), 100 W (1/8 HP)	Motor case, gear case and terminal box: Aluminum Output shaft: S45C Screws: Stainless steel (externally facing screws only)	Motor case, gear case, terminal box: Painted (excluding installation surface)

Note

No built-in overheat protection device (thermal protector).

When there is an overload or the output shaft is locked, use the electromagnetic switch and the inverter's electronic thermal function to prevent motor burnout.

### **CR Circuit for Surge Suppression**

This product is used to protect the contacts of the relay or switch used in the forward/reverse circuit section or the instantaneous stop circuit section of a motor.

### Product Line

Product Name	List Price		
EPCR1201-2	\$5.00		

250 VAC (120  $\Omega$ , 0.1  $\mu$ F)



### Peripheral Equipment (Sold separately)

### Torque Arms

A torque arm acts as an anti-spin mechanism when a right-angle shaft, hollow hypoid JH gear is installed to prevent gearheads from rotating due to reactive force from shafts being driven.





**TAF2S-15-NS** 

#### Product Line

Product Name	Applicable Product	Major	List Price
TAF2S-12-NS	4IK25KIII-4HIIB, 4IK30VKIIIT-4HIIS		24.00
TAF2S-15-NS	5IK40K  -5H  B, 5IK40VK  T-5H  S 5IK60K  -5H  B 5IK90K  -5H  B, 5IK100VK  T-5H  S	Material: SS400 Surface treatment: Trivalent chromate	25.00

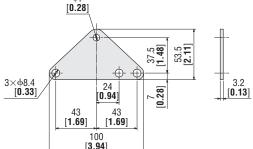
<sup>●</sup> A symbol indicating the power supply voltage (KIIS Series: ES KII Series: JC) is specified where the box 🗐 is located in the applicable product. A number indicating the gear ratio is specified where the box  $\square$  is located in the applicable product.

### Dimensions Unit = mm (in)

### **♦ TAF2S-12-NS**

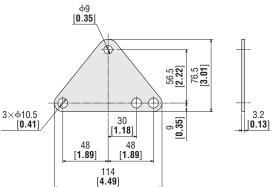
Mass: 75 g (2.65 oz) 2D CAD A1608 3D CAD

[0.28]



### **♦ TAF2S-15-NS** Mass: 125 g (4.4 oz)

2D CAD A1609 3D CAD



Specifications are subject to change without notice. This catalog was published in June, 2019.

### ORIENTAL MOTOR U.S.A. CORP.

Western Sales and **Customer Service Center** 

Tel: (310) 715-3301 Fax: (310) 225-2594

Los Angeles

Tel: (310) 715-3301

San Jose

Tel: (408) 392-9735

Seattle

Tel: (425) 214-7559

Midwest Sales and **Customer Service Center** 

Tel: (847) 871-5900 Fax: (847) 472-2623

Chicago

Tel: (847) 871-5900

Detroit

Tel: (734) 808-0003

**Dallas** 

Tel: (214) 432-3386

**Toronto** 

Tel: (905) 502-5333

**Eastern Sales and Customer Service Center** Tel: (781) 848-2426 Fax: (781) 848-2617

Tel: (781) 848-2426

Charlotte

Tel: (704) 766-1335

**New York** 

Tel: (973) 359-1100 Philadelphia

Tel: (610) 605-3103

Tampa

Tel: (813) 402-4439

Obtain Specifications, Online Training and Purchase Products at: www.orientalmotor.com

### **Technical Support**

Tel: (800) 468-3982 / 8:30 A.M. to 5:00 P.M., P.S.T. (M-F) 7:30 A.M. to 5:00 P.M., C.S.T. (M-F)

E-mail: techsupport@orientalmotor.com

Copyright ©2018 ORIENTAL MOTOR U.S.A. CORP This printed material uses ECF (Elemental Chlorine Free) paper and vegetable oil based inks.

This combination is environmentally friendly.