



## OPERATING MANUAL

Stepping Motor **αSTEP**  
**AZ Series Motor**



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## Introduction

### ■ Before use

Only qualified personnel of electrical and mechanical engineering should work with the product.  
 Use the product correctly after thoroughly reading the "Safety precautions." In addition, be sure to observe the contents described in warning, caution, and note in this manual.  
 The product described in this manual has been designed and manufactured to be incorporated in general industrial equipment. Do not use for any other purpose. Oriental Motor Co., Ltd. is not responsible for any damage caused through failure to observe this warning.

### ■ Related operating manuals

For operating manuals not included with the product, contact your nearest Oriental Motor sales office or download from Oriental Motor Website Download Page.

Operating manual name	Included or not included with product
<b>AZ Series OPERATING MANUAL Motor</b> (this document)	Included
<b>AZ Series/Motorized actuator equipped with AZ Series Function Edition</b>	Not included
APPENDIX UL Standards for <b>AZ Series</b>	Included

## Safety precautions

The precautions described below are intended to prevent danger or injury to the user and other personnel through safe, correct use of the product. Use the product only after carefully reading and fully understanding these instructions.

### Description of signs

	Handling the product without observing the instructions that accompany a "WARNING" symbol may result in serious injury or death.
	Handling the product without observing the instructions that accompany a "CAUTION" symbol may result in injury or property damage.
	The items under this heading contain important handling instructions that the user should observe to ensure the safe use of the product.

Thank you for purchasing an Oriental Motor product. This Operating Manual describes product handling procedures and safety precautions.

- Please read it thoroughly to ensure safe operation.
- Always keep the manual where it is readily available.

### Description of graphic symbols

	Indicates "prohibited" actions that must not be performed.
	Indicates "compulsory" actions that must be performed.

<b>WARNING</b>	
	Do not use the product in explosive or corrosive environments, in the presence of flammable gases, locations subjected to splashing water, or near combustibles. Doing so may result in fire, electric shock or injury.
	Do not transport, install the product, perform connections or inspections when the power is on. Doing so may result in electric shock.
	Do not forcibly bend, pull or pinch the cable. Doing so may result in fire or electric shock.
	Do not disassemble or modify the product. Doing so may result in injury or damage to equipment.
	Assign qualified personnel the task of installing, wiring, operating/controlling, inspecting, and troubleshooting the product. Failure to do so may result in fire, electric shock, injury or damage to equipment.
	Take measures to keep the moving part in position if the product is used in vertical operations such as elevating equipment. Failure to do so may result in injury or damage to equipment.
	Do not use the brake mechanism of the electromagnetic brake motor for braking or as a safety brake. Doing so may result in injury or damage to equipment.
	If the driver generates an alarm (any of the driver protective functions is triggered), the motor stops and loses its holding torque. Take measures to keep the moving part in position. Failure to do so may result in injury or damage to equipment.
	Install the product inside an enclosure. Failure to do so may result in electric shock or injury.
	The product is Class I equipment. When installing the product, install it inside an enclosure so that it is out of the direct reach of users. Be sure to ground if users can touch it. Failure to do so may result in electric shock.

<b>CAUTION</b>	
	Do not use the product beyond its specifications. Doing so may result in electric shock, injury or damage to equipment.
	Keep your fingers and objects out of the openings in the product. Failure to do so may result in fire, electric shock or injury.
	Do not touch the product during operation or immediately after stopping. Doing so may result in a skin burn(s).
	Do not carry the motor by holding the motor output shaft or motor cable. Doing so may result in injury.
	Keep the area around the product free of combustible materials. Failure to do so may result in fire or a skin burn(s).
	Leave nothing around the product that would obstruct ventilation. Failure to do so may result in damage to equipment.

<b>⚠ CAUTION</b>	
	Do not touch the rotating part (output shaft) during operation. Doing so may result in injury.
	Do not touch the terminals while conducting the insulation resistance measurement or dielectric strength test. Doing so may result in electric shock.
	Provide a cover over the rotating part (output shaft) of the motor. Failure to do so may result in injury.
	Use a motor and driver only in the specified combination. Failure to do so may result in fire.
	Provide an emergency stop device or emergency stop circuit external to the equipment so that the entire equipment will operate safely in the event of a system failure or malfunction. Failure to do so may result in injury.
	The motor surface temperature may exceed 70 °C (158 °F) even under normal operating conditions. If the operator is allowed to approach the motor in operation, affix a warning label shown in the figure on a conspicuous position. Failure to do so may result in a skin burn(s).
	 Warning label

## Precautions for use

This section covers restrictions and requirements the user should consider when using the product.

- **Be sure to use the accessory cable to connect the motor and driver.**
- **When conducting the insulation resistance measurement or the dielectric strength test, be sure to separate the connection between the motor and the driver.**

Conducting the insulation resistance measurement or dielectric strength test with the motor and driver connected may result in damage to the product.

- **Make sure not to hit or apply a strong impact on the motor output shaft or the encoder (ABZO sensor).**

Applying a strong impact on the motor output shaft or the encoder (ABZO sensor) may cause encoder (ABZO sensor) damage or motor malfunction. The warning label shown in the right is attached on the motor.



Warning label

- **Do not move the encoder (ABZO sensor) toward a strong magnetic field.**

A magnetic sensor is built into the encoder (ABZO sensor). If the motor is installed close to equipment which generates a strong magnetic field, the encoder (ABZO sensor) may break or malfunction. Especially, since the motors of frame size 20 mm (0.79 in.) and 28 mm (1.10 in.) are easily affected by a magnetic field, so make sure the environment at transportation and storage as well as the installation location in use. Keep the magnetic flux density on the surface of the encoder (ABZO sensor) so as not to exceed the values in the table.

Motor frame size	Magnetic flux density	
	When transporting and storing	When operating
28 mm (1.10 in.) or less	5 mT	2 mT *
42 mm (1.65 in.) or more	10 mT	10 mT

\* When the magnetic flux density is exceeding 1 mT and 2 mT or less, use in an environment where the operating ambient temperature is exceeding 20 °C (68 °F) and 40 °C (104 °F) or less.

- **Meshing noise of mechanical sensor**

A gear type mechanical sensor is built into the encoder (ABZO sensor). Although the meshing noise of gears may generate, it is not malfunction.

- **Do not apply a radial load and axial load in excess of the specified permissible limit**

Operating the motor under an excessive radial load or axial load may damage the motor bearings (ball bearings). Be sure to operate the motor within the specified permissible limit of radial load and axial load.

- **Use the motor in conditions where its surface temperature will not exceed 80 °C (176 °F).**

The surface temperature on the motor case may exceed 80 °C (176 °F) depending on operating conditions such as ambient temperature, operating speed, duty cycle, and others. In order to protect the encoder (ABZO sensor), use the motor so that the surface temperature on the motor case does not exceed 80 °C (176 °F). If the encoder (ABZO sensor) temperature reaches the upper limit, the motor overheat protection alarm will generate. Use the geared motor in a condition where the gear case temperature does not exceed 70 °C (158 °F), in order to prevent deterioration of grease and parts in the gear case.

- **Holding torque at standstill**

The motor holding torque is reduced by the current cutback function of the driver at motor standstill. When selecting a motor, check the holding torque at motor standstill in the specifications on the catalog.

- **Do not use the electromagnetic brake to reduce speed or as a safety brake.**

Do not use the electromagnetic brake as a means to decelerate and stop the motor. The brake hub of the electromagnetic brake will wear significantly and the braking force will drop. Since the power off activated type electromagnetic brake is equipped, it helps maintain the position of the load when the power is cut off, but this brake cannot securely hold the load in place. Accordingly, do not use the electromagnetic brake as a safety brake. To use the electromagnetic brake to hold the load in place, do so after the motor has stopped.

- **Preventing electrical noise**

For measures with regard to noise, refer to the [OPERATING MANUAL Driver](#).

- **Make sure to provide measures so that the key is not flown off when operating the motor with key in a state where a load is not installed.**

Flying off the key may result in injury or damage to equipment.

- **Grease of encoder (ABZO sensor) and geared motor**

On rare occasions, a small amount of grease may ooze out from the following places.

- Encoder (ABZO sensor) mechanical part [motors of frame size 20 mm (0.79 in.) and 28 mm (1.10 in.)]
- Geared motor

If there is concern over possible environmental damage resulting from the leakage of grease, check for grease stains during regular inspections. Alternatively, install an oil pan or other device to prevent leakage from causing further damage. Oil leakage may lead to problems in the customer's equipment or products.

- **Peak torque of geared motor**

Always operate the geared motor under a load not exceeding the peak torque. If the load exceeds the peak torque, the gear will be damaged.

- **Rotation direction of the gear output shaft**

The relationship between the rotation direction of the motor shaft and that of the gear output shaft changes as follows, depending on the gear type and gear ratio.

Type of gear	Gear ratio	Rotation direction (relative to the motor rotation direction)
<b>TS</b> geared	3,6, 7,2, 10	Same direction
	20, 30	Opposite direction
<b>FC</b> geared, <b>PS</b> geared, <b>HPG</b> geared	All gear ratios	Same direction
Harmonic geared	All gear ratios	Opposite direction

- Do not perform push-motion operation with geared motor.

Doing so may cause damage to the motor or gear part.

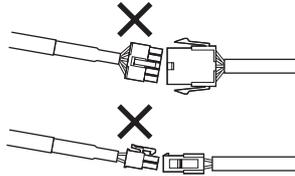
## ■ Notes when the connection cable is used

Note the following points when an accessory cable is used.

### • When inserting the connector

Hold the connector main body, and insert it in straight securely.

Inserting the connector in a inclined state may result in damage to terminals or a connection failure.

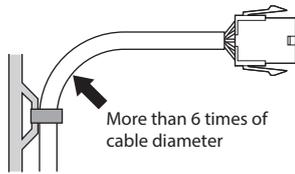


### • When pulling out the connector

Pull out the connector in straight while releasing the lock part of the connector. Pulling out the connector with holding the cable (lead wires) may result in damage to the connector.

### • Bending radius of cable

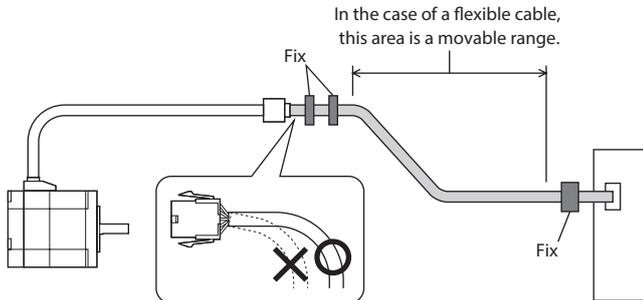
Use the cable in a state where the bending radius of the cable is more than six times of the cable diameter. In the case of the lead wire type, use in a state where the bending radius is more than four times of the diameter of the lead wires.



### • How to fix the cable

Fix the cable at the positions near the connector so as to apply no stress on the connector part.

Take measures so as to apply no stress on the connector by using wide clamps or by fixing at two places.



## Preparation

### ■ Checking the product

Verify that the items listed below are included. Report any missing or damaged items to the Oriental Motor sales office from which you purchased the product.

- Motor ..... 1 unit
- Parallel key ..... 1 pc. \*1
- Motor mounting screw (M4)..... 4 pcs. \*2
- Motor mounting screw (M8)..... 4 pcs. \*3
- OPERATING MANUAL Motor ..... 1 copy (thid document)
- APPENDIX UL Standards for **AZ** Series ..... 1 copy \*4

\*1 Included with standard type motor with key and geared type (except for the **AZM24-PS**, **AZM24-HS**, **AZM46-TS** geared type, and the **HPG** geared flange output type)

\*2 Included with **AZM66-TS** geared type.

\*3 Included with **AZM98-TS** geared type.

\*4 Included with products conform to the UL Standards.

## ■ How to identify the product model

Check the model number of the motor against the number shown on the nameplate.

### ● Standard type

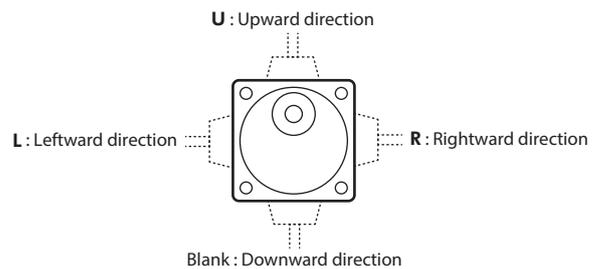
**AZM** **6** **6** **A** **0** **K** **F**  
 1 2 3 4 5 6 7

### ● Geared type (excluding the FC geared)

**AZM** **6** **6** **A** **C** - **HP** **15** **F**  
 1 2 3 4 6 8 9 10

1	Series name	<b>AZM: AZ</b> Sereis motor
2	Motor frame size	<b>1:</b> 20 mm (0.79 in.) <b>2:</b> 28 mm (1.10 in.) [30 mm (1.18 in.) for Harmonic geared type] <b>4:</b> 42 mm (1.65 in.) [40 mm (1.57 in.) for <b>HPG</b> geared type] <b>6:</b> 60 mm (2.36 in.) <b>9:</b> 85 mm (3.35 in.) [90 mm (3.54 in.) for geared type]
3	Motor length	
4	Motor shaft features	<b>A:</b> Single shaft <b>M:</b> With electromagnetic brake
5	Additional function	<b>O:</b> Round shaft type <b>1:</b> With key Blank: Round shaft with shaft flat on one side
6	Motor power supply input	<b>C:</b> AC power input type <b>K:</b> DC power input type
7	Cable outlet direction	<b>F:</b> Horizontal direction with respect to motor (DC power input type only)
8	Type of gear	<b>TS:</b> <b>TS</b> geared <b>HP:</b> <b>HPG</b> geared <b>PS:</b> <b>PS</b> geared <b>HS:</b> Harmonic geared
9	Gear ratio	
10	Varies depending on the gear type.	<ul style="list-style-type: none"> <li>• <b>TS</b> geared type: Cable outlet direction *               <ul style="list-style-type: none"> <li><b>U:</b> Upward direction</li> <li><b>R:</b> Rightward direction</li> <li><b>L:</b> Leftward direction</li> <li>Blank: Downward direction</li> </ul> </li> <li>• <b>HPG</b> geared type: Output shaft type               <ul style="list-style-type: none"> <li>Blank: Shaft output type</li> <li><b>F:</b> Flange output type</li> </ul> </li> </ul>

\* The cable outlet direction represents the one as viewed from the output shaft side in a state of placing it upward.

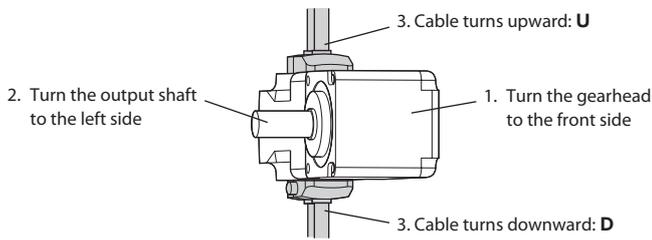


## ● FC geared type

AZM 6 6 A C - FC 7.2 U A  
 1 2 3 4 5 6 7 8 9

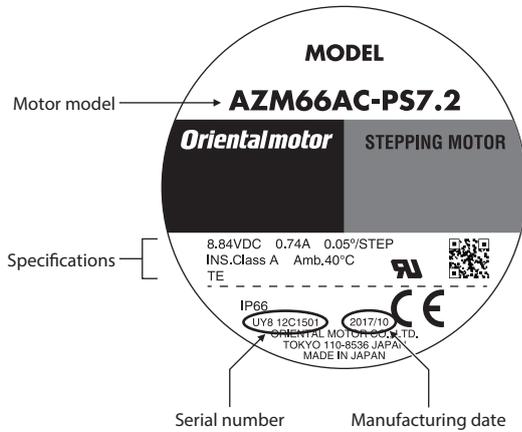
1	Series name	<b>AZM: AZ</b> Sereis motor
2	Motor frame size	<b>4:</b> 42 mm (1.65 in.) <b>6:</b> 60 mm (2.36 in.)
3	Motor length	
4	Motor shaft features	<b>A:</b> Single shaft <b>M:</b> With electromagnetic brake
5	Motor power supply input	<b>C:</b> AC power input type <b>K:</b> DC power input type
6	Type of gear	<b>FC:</b> FC geared
7	Gear ratio	
8	Cable outlet direction *	<b>D:</b> Downward direction <b>U:</b> Upward direction
9	Motor identification	<b>A:</b> Solid shaft

\* Check the cable outlet direction as shown in the figure.



## ■ Information about nameplate

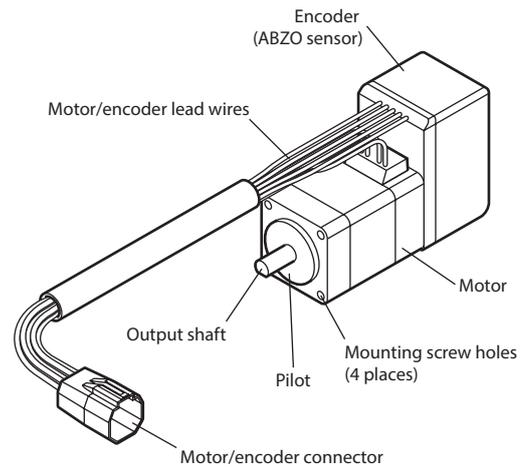
The figure shows an example.



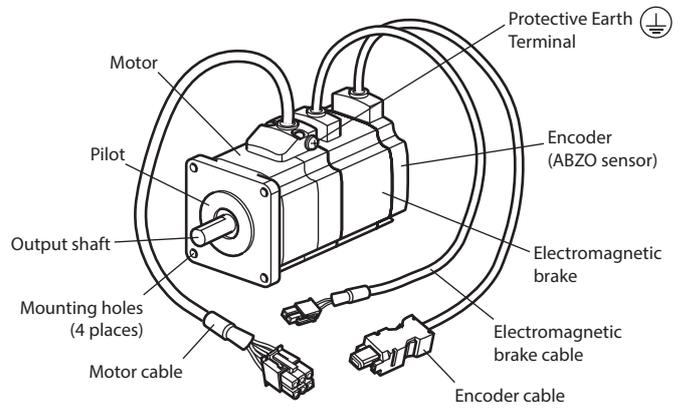
The position describing the information may vary depending on the product.

## ■ Names of parts

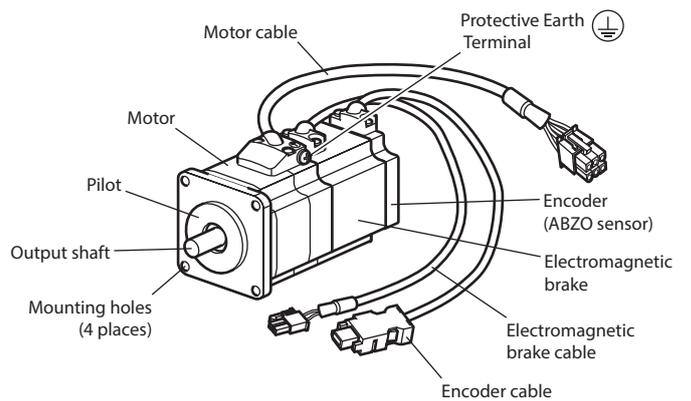
### ● Standard type (Example: AZM14AK)



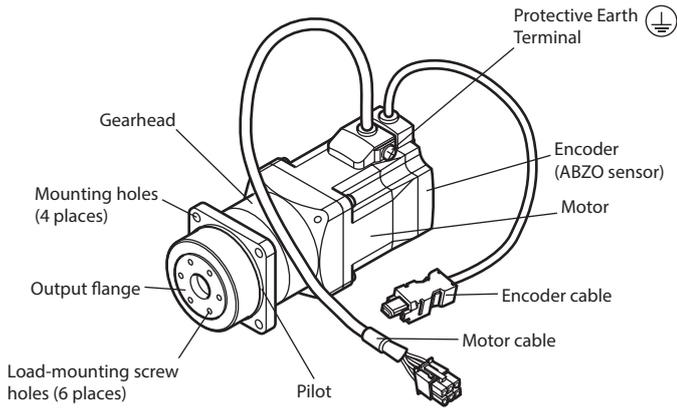
### ● Standard type with electromagnetic brake (Example: AZM66MC)



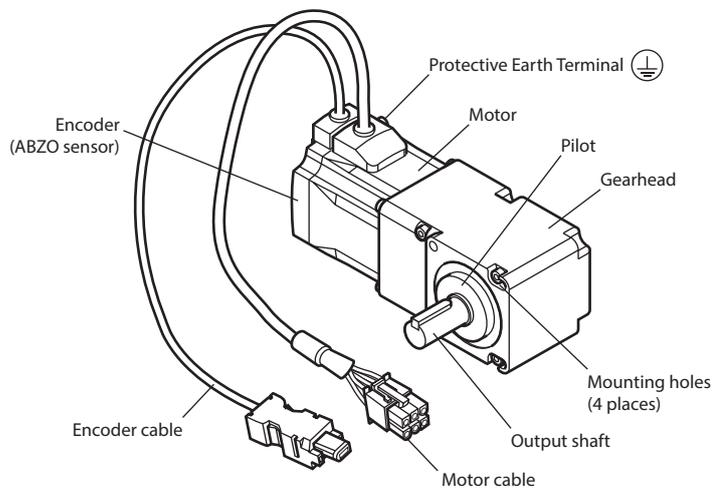
### ● Standard type Cable outlet in horizontal direction (Example: AZM66M0KF)



● **HPG geared flange output type**  
(Example: AZM66AC-HP5F)



● **FC geared type** (Example: AZM66AC-FC7.2UA)



● **If a motor is installed in an environment where a magnetic field is generated**

A magnetic sensor is built into the encoder (ABZO sensor). If the motor is installed close to equipment which generates a strong magnetic field, the encoder (ABZO sensor) may break or malfunction. Keep the magnetic flux density on the surface of the encoder (ABZO sensor) so as not to exceed the values in the table.

Motor frame size	Magnetic flux density
28 mm (1.10 in.) or less	2 mT *
42 mm (1.65 in.) or more	10 mT

\* When the magnetic flux density is exceeding 1 mT and 2 mT or less, use in an environment where the operating ambient temperature is exceeding 20 °C (68 °F) and 40 °C (104 °F) or less.

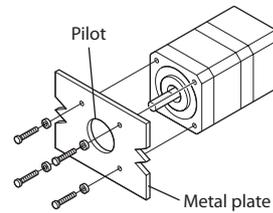


Do not install the motor close to equipment which generates a strong magnetic field.

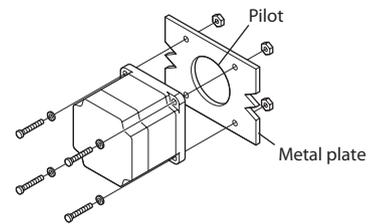
■ **Installation method**

The motor can be installed in any direction. To allow for heat dissipation and prevent vibration, install the motor on a metal surface of sufficient strength.

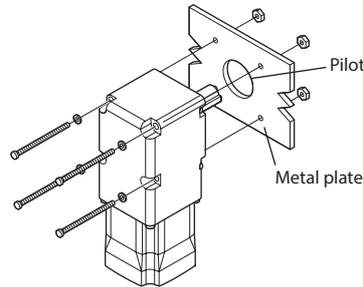
● **Installation method A**



● **Installation method B**



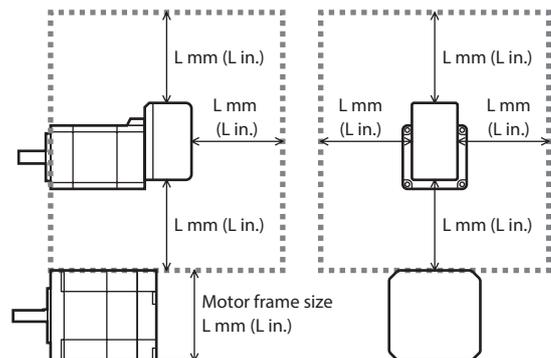
● **Installation method B (For FC geared type)**



● **Installation for motors of frame size 20 mm (0.79 in.) and 28 mm (1.10 in.)**

Since the encoder (ABZO sensor) for the motors of frame size 20 mm (0.79 in.) and 28 mm (1.10 in.) are easily affected by a magnetic field, make sure the installation location.

When motors are installed side by side, ensure the distance among motors of more than the frame size in horizontal and vertical directions.



\* Ensure the distance of more than the frame size [L mm (L in.)].

**Installation**

■ **Location for installation**

The motor has been designed and manufactured to be incorporated in equipment. Install it in a well-ventilated location that provides easy access for inspection.

The location must also satisfy the following conditions:

- Inside an enclosure that is installed indoors (provide vent holes)
- Operating ambient temperature: 0 to +40 °C (+32 to +104 °F) (non-freezing)
- Operating ambient humidity 85% or less (non-condensing)
- Area that is free of explosive atmosphere or toxic gas (such as sulfuric gas) or liquid
- Area not exposed to direct sun
- Area free of excessive amount of dust, iron particles or the like
- Area not subject to splashing water (rain, water droplets), oil (oil droplets) or other liquids
- Area free of excessive salt
- Area not subject to continuous vibration or excessive shocks
- Area free of excessive electromagnetic noise (from welders, power machinery, etc.)
- Area free of radioactive materials, magnetic fields or vacuum
- 1,000 m (3,300 ft.) or lower above sea level

## ● Nominal size, tightening torque and installation method

### ● Standard type

Motor model	Nominal size	Tightening torque [N·m (oz-in)]	Effective depth of screw thread [mm (in.)]	Installation method
<b>AZM14</b> <b>AZM15</b>	M2	0.25 (35)	2.5 (0.098)	A
<b>AZM24</b> <b>AZM26</b>	M2.5	0.5 (71)	2.5 (0.098)	A
<b>AZM46</b> <b>AZM48</b>	M3	1 (142)	4.5 (0.177)	A
<b>AZM66</b> <b>AZM69</b>	M4	2 (280)	–	B
<b>AZM98</b> <b>AZM911</b>	M6	3 (420)	–	B

### ● TS geared type

Motor model	Nominal size	Tightening torque [N·m (oz-in)]	Effective depth of screw thread [mm (in.)]	Installation method
<b>AZM46</b>	M4	1.4 (198)	8 (0.315)	A
<b>AZM66</b>	M4	1.4 (198)	–	B
<b>AZM98</b>	M8	4 (560)	–	B

### ● FC geared type

Motor model	Nominal size	Tightening torque [N·m (oz-in)]	Effective depth of screw thread [mm (in.)]	Installation method
<b>AZM46</b>	M4	2 (280)	–	B
<b>AZM66</b>	M5	2.5 (350)	–	B

### ● PS geared type

Motor model	Nominal size	Tightening torque [N·m (oz-in)]	Effective depth of screw thread [mm (in.)]	Installation method
<b>AZM24</b>	M3	1 (142)	6 (0.236)	A
<b>AZM46</b>	M4	2 (280)	8 (0.315)	A
<b>AZM66</b>	M5	2.5 (350)	10 (0.394)	A
<b>AZM98</b>	M8	4 (560)	15 (0.591)	A

### ● HPG geared type

Motor model	Nominal size	Tightening torque [N·m (oz-in)]	Effective depth of screw thread [mm (in.)]	Installation method
<b>AZM46</b>	M3	1 (142)	–	B
<b>AZM66</b>	M5	2.5 (350)	–	B
<b>AZM98</b>	M8	4 (560)	–	B

### ● Harmonic geared type

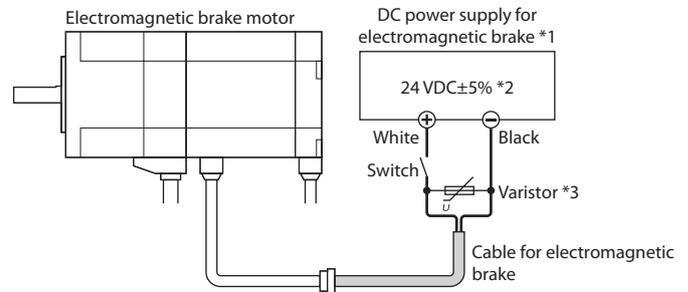
Motor model	Nominal size	Tightening torque [N·m (oz-in)]	Effective depth of screw thread [mm (in.)]	Installation method
<b>AZM24</b>	M3	1 (142)	6 (0.236)	A
<b>AZM46</b>	M4	2 (280)	8 (0.315)	A
<b>AZM66</b>	M5	2.5 (350)	10 (0.394)	A
<b>AZM98</b>	M8	4 (560)	–	B

## ■ Installing a load

When installing a load to the motor, align the centers of the motor output shaft and load shaft. When installing a coupling or pulley on the motor output shaft, do so without damaging the output shaft and bearings (ball bearings).

### ● Electromagnetic brake motor

To release the electromagnetic brake and install the load, a DC power supply is needed to power the electromagnetic brake. Connect the DC power supply (24 VDC±5%) to the motor using the "cable for electromagnetic brake."



\*1 The power supply current capacities are as follows.

**AZM46:** 0.08 A or more

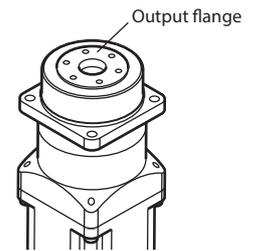
**AZM66, AZM69, AZM98:** 0.25 A or more

\*2 If the distance between the motor and driver is extended to 20 m (65.6 ft.), use a power supply of 24 VDC±4%.

\*3 Provide a varistor to protect the contact of the switch or to prevent electrical noise. [Recommended varistor: Z15D121 (SEMITEC Corporation)].

### ● HPG geared flange output type

When installing a load on the **HPG** geared flange output type, use the load mounting holes on the output flange.



### Load mounting hole

Motor model	Number of screw holes	Nominal size	Tightening torque [N·m (oz-in)]	Effective depth of screw thread [mm (in.)]
<b>AZM46</b>	3 places	M4	4.5 (630)	6 (0.236)
<b>AZM66</b>	6 places	M4	4.5 (630)	7 (0.276)
<b>AZM98</b>	6 places	M6	15.3 (2,100)	10 (0.394)



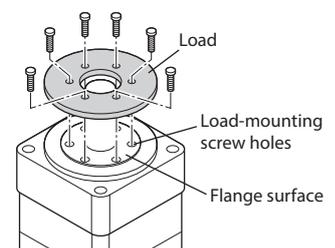
Since the tightening torque for the load mounting screw is large, using a mechanically weak load or screws may cause damage. Satisfy the following conditions for the load and mounting screws. Also, be sure to tighten with the specified torque.

Material of load: Steel

Mounting screw: Use a screw which tensile strength ranking is 12.9 or higher

### ● When a load is installed on the flange face of the Harmonic geared type

With a Harmonic geared type (excluding **AZM98**), a load can be installed directly on the gear using the load-mounting screw holes provided on the flange surface.



## Load-mounting screw hole

Motor model	Nominal size	Number of screws	Tightening torque [N·m (oz-in)]	Effective depth of screw thread [mm (in.)]
AZM24	M3	4	1.4 (198)	4 (0.16)
AZM46	M3	6	1.4 (198)	5 (0.20)
AZM66	M4	6	2.5 (350)	6 (0.24)

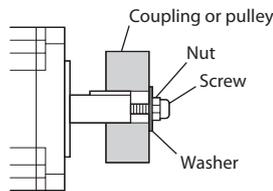


- When installing a load on the flange surface, the load cannot be mounted using the key slot in the output shaft.
- Design an appropriate installation layout so that the load will not contact the metal plate or screws used for installing the motor.

## When a coupling or a pulley is installed

When installing a coupling or pulley on the output shaft, do not apply a strong force to the output shaft. For the standard type motor, in particular, a mechanical impact may cause damage to the encoder (ABZO sensor). When installing a coupling or pulley on the standard type motor with a parallel key, utilize the screw hole on the shaft end.

- Install a coupling (pulley) on the motor output shaft.
- Install a screw, nut, and washer on the end of the output shaft, and push the coupling (pulley) and secure with tightening the screw.



## Permissible radial load, permissible axial load and permissible moment load



Failure due to fatigue may occur when the motor bearings and output shaft are subject to repeated loading by a radial or axial load that is in excess of the permissible limit.



The permissible radial load and permissible axial load of the **PS** geared type and **HPG** geared type represent the value that the service life of the gear part satisfies 20,000 hours when either of the radial load or axial load is applied to the gear output shaft.

## Permissible radial load

### Standard type

Motor model	Permissible radial load [N (lb.)]				
	Distance from the tip of motor output shaft [mm (in.)]				
	0 (0)	5 (0.2)	10 (0.39)	15 (0.59)	20 (0.79)
AZM14 AZM15	12 (2.7)	15 (3.3)	–	–	–
AZM24 AZM26	25 (5.6)	34 (7.6)	52 (11.7)	–	–
AZM46	35 (7.8)	44 (9.9)	58 (13)	85 (19.1)	–
AZM48	30 (6.7)	35 (7.8)	44 (9.9)	58 (13)	85 (19.1)
AZM66 AZM69	90 (20)	100 (22)	130 (29)	180 (40)	270 (60)
AZM98 AZM911	260 (58)	290 (65)	340 (76)	390 (87)	480 (108)

## TS geared type

Motor model	Gear ratio	Permissible radial load [N (lb.)]				
		Distance from the tip of motor output shaft [mm (in.)]				
		0 (0)	5 (0.2)	10 (0.39)	15 (0.59)	20 (0.79)
AZM46	3.6, 7.2, 10	20 (4.5)	30 (6.7)	40 (9)	50 (11.2)	–
	20, 30	40 (9)	50 (11.2)	60 (13.5)	70 (15.7)	–
AZM66	3.6, 7.2, 10	120 (27)	135 (30)	150 (33)	165 (37)	180 (40)
	20, 30	170 (38)	185 (41)	200 (45)	215 (48)	230 (51)
AZM98	3.6, 7.2, 10	300 (67)	325 (73)	350 (78)	375 (84)	400 (90)
	20, 30	400 (90)	450 (101)	500 (112)	550 (123)	600 (135)

## FC geared type

Motor model	Gear ratio	Permissible radial load [N (lb.)]				
		Distance from the tip of motor output shaft [mm (in.)]				
		0 (0)	5 (0.2)	10 (0.39)	15 (0.59)	20 (0.79)
AZM46	All gear ratios	180 (40)	200 (45)	220 (49)	250 (56)	–
AZM66	All gear ratios	270 (60)	290 (65)	310 (69)	330 (74)	350 (78)

## PS geared type

Motor model	Gear ratio	Permissible radial load [N (lb.)]				
		Distance from the tip of motor output shaft [mm (in.)]				
		0 (0)	5 (0.2)	10 (0.39)	15 (0.59)	20 (0.79)
AZM24	All gear ratios	45 (10.1)	60 (13.5)	80 (18)	100 (22)	–
	5	70 (15.7)	80 (18)	95 (21)	120 (27)	–
AZM46	7.2	80 (18)	90 (20)	110 (24)	140 (31)	–
	10	85 (19.1)	100 (22)	120 (27)	150 (33)	–
	25	120 (27)	140 (31)	170 (38)	210 (47)	–
	36	130 (29)	160 (36)	190 (42)	240 (54)	–
	50	150 (33)	170 (38)	210 (47)	260 (58)	–
AZM66	5	170 (38)	200 (45)	230 (51)	270 (60)	320 (72)
	7.2	200 (45)	220 (49)	260 (58)	310 (69)	370 (83)
	10	220 (49)	250 (56)	290 (65)	350 (78)	410 (92)
	25	300 (67)	340 (76)	400 (90)	470 (105)	560 (126)
	36	340 (76)	380 (85)	450 (101)	530 (119)	630 (141)
AZM98	50	380 (85)	430 (96)	500 (112)	600 (135)	700 (157)
	5	380 (85)	420 (94)	470 (105)	540 (121)	630 (141)
	7.2	430 (96)	470 (105)	530 (119)	610 (137)	710 (159)
	10	480 (108)	530 (119)	590 (132)	680 (153)	790 (177)
	25	650 (146)	720 (162)	810 (182)	920 (200)	1,070 (240)
AZM98	36	730 (164)	810 (182)	910 (200)	1,040 (230)	1,210 (270)
	50	820 (184)	910 (200)	1,020 (220)	1,160 (260)	1,350 (300)

## HPG geared shaft output type

Motor model	Gear ratio	Permissible radial load [N (lb.)]				
		Distance from the tip of motor output shaft [mm (in.)]				
		0 (0)	5 (0.2)	10 (0.39)	15 (0.59)	20 (0.79)
AZM46	5	150 (33)	170 (38)	190 (42)	230 (51)	270 (60)
	9	180 (40)	200 (45)	230 (51)	270 (60)	320 (72)
AZM66	5	250 (56)	270 (60)	300 (67)	330 (74)	360 (81)
	15	360 (81)	380 (85)	420 (94)	460 (103)	510 (114)
AZM98	5	600 (135)	630 (141)	670 (150)	710 (159)	750 (168)
	15	830 (186)	880 (198)	930 (200)	980 (220)	1,050 (230)

• Harmonic geared type

Motor model	Gear ratio	Permissible radial load [N (lb.)]				
		Distance from the tip of motor output shaft [mm (in.)]				
		0 (0)	5 (0.2)	10 (0.39)	15 (0.59)	20 (0.79)
<b>AZM24</b>	All gear ratios	100 (22)	135 (30)	175 (39)	250 (56)	–
<b>AZM46</b>		180 (40)	220 (49)	270 (60)	360 (81)	510 (114)
<b>AZM66</b>		320 (72)	370 (83)	440 (99)	550 (123)	720 (162)
<b>AZM98</b>		1,090 (240)	1,150 (250)	1,230 (270)	1,310 (290)	1,410 (310)

● Permissible axial load

Type	Motor model	Gear ratio	Permissible axial load [N (lb.)]
Standard	<b>AZM14</b> <b>AZM15</b>	–	3 (0.67)
	<b>AZM24</b> <b>AZM26</b>		5 (1.12)
	<b>AZM46</b> <b>AZM48</b>		15 (3.3)
	<b>AZM66</b> <b>AZM69</b>		30 (6.7)
	<b>AZM98</b> <b>AZM911</b>		60 (13.5)
TS geared	<b>AZM46</b>	All gear ratios	15 (3.3)
	<b>AZM66</b>		40 (9)
	<b>AZM98</b>		150 (33)
FC geared	<b>AZM46</b>	All gear ratios	100 (22)
	<b>AZM66</b>		200 (45)
PS geared	<b>AZM24</b>	All gear ratios	40 (9)
	<b>AZM46</b>		100 (22)
	<b>AZM66</b>		200 (45)
	<b>AZM98</b>		600 (135)
HPG geared	<b>AZM46</b>	5	430 (96)
		9	510 (114)
	<b>AZM66</b>	5	700 (157)
		15	980 (220)
		<b>AZM98</b>	5
15	2,030 (450)		
Harmonic geared	<b>AZM24</b>	All gear ratios	140 (31)
	<b>AZM46</b>		220 (49)
	<b>AZM66</b>		450 (101)
	<b>AZM98</b>		1,300 (290)

● Permissible moment load

When installing an arm or table on the flange surface, calculate the moment load using the formula below if the flange surface receives any eccentric load. The moment load should not exceed the permissible value specified in the table.

• HPG geared flange output type

Motor model	Gear ratio	Permissible moment load [N·m (oz-in)]
<b>AZM46</b>	5	4.9 (43)
	9	5.9 (52)
<b>AZM66</b>	5	12 (106)
	15	17.2 (152)
<b>AZM98</b>	5	38.7 (340)
	15	53.5 (470)



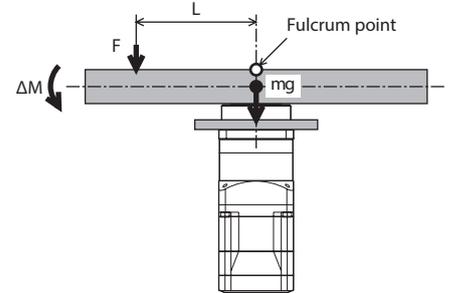
The permissible moment load of the **HPG** geared type represents the value that the service life of the gear part satisfies 20,000 hours.

How to read a code

- m: Mass of a load (kg)
- g: Gravitational acceleration (m/s<sup>2</sup>)
- F: External force (N)
- L: Overhang distance (m)
- a: Constant (m)
- ΔF: Load applied on the output flange surface (N)
- Fs: Permissible axial load (N)
- ΔM: Load moment (N·m)
- M: Permissible moment load (N·m)

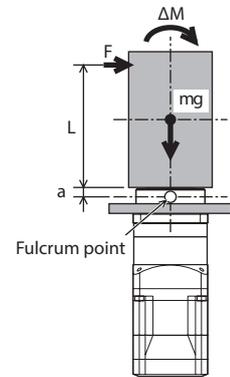
**Example 1; When an external force F(N) is applied on a position overhanging by L (m) from the center of the output flange in the horizontal direction**

- Load moment  
ΔM = F · L  
ΔM ≤ M
- Axial load  
ΔF = F + m · g  
ΔF ≤ Fs



**Example 2; When an external force F(N) is applied on a position overhanging by L (m) from the output flange mounting surface in the vertical direction**

- Load moment  
ΔM = F · (L + a)  
ΔM ≤ M
- Axial load  
ΔF = m · g  
ΔF ≤ Fs



Motor model	Coefficient "a"
<b>AZM46</b>	0.006
<b>AZM66</b>	0.011
<b>AZM98</b>	0.0115

• Harmonic geared type

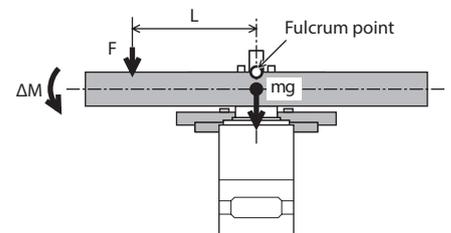
The **AZM98** type is excluded.

How to read a code

- m: Mass of a load (kg)
- g: Gravitational acceleration (m/s<sup>2</sup>)
- F: External force (N)
- L: Overhang distance (m)
- a: Constant (m)
- ΔF: Load applied on the output flange surface (N)
- Fs: Permissible axial load (N)
- ΔM: Load moment (N·m)
- M: Permissible moment load (N·m)

**Example 1; When an external force F(N) is applied on a position overhanging by L (m) from the center of the output flange in the horizontal direction**

- Load moment  
ΔM = F · L  
ΔM ≤ M
- Axial load  
ΔF = F + m · g  
ΔF ≤ Fs

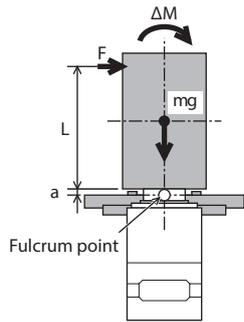


Motor model	Permissible moment load (N·m)
<b>AZM24</b>	2.9
<b>AZM46</b>	5.6
<b>AZM66</b>	11.6

**Example 2; When an external force F(N) is applied on a position overhanging by L (m) from the output flange mounting surface in the vertical direction**

- Load moment  
 $\Delta M = F \cdot (L + a)$   
 $\Delta M \leq M$
- Axial load  
 $\Delta F = m \cdot g$   
 $\Delta F \leq F_s$

Motor model	Coefficient "a"
<b>AZM24</b>	0.0073
<b>AZM46</b>	0.009
<b>AZM66</b>	0.0114



## Grounding the motor

The grounding method of the motor varies depending on the driver input power. Check the table and ground using a suitable method. Be sure to ground the driver.

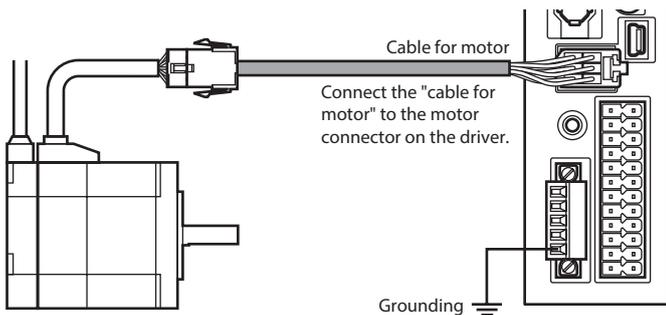
Grounding method	Driver input voltage		
	100-120 VAC 200-240 VAC	24 VDC	48 VDC
1) Protective Earth Terminal of the driver	Required to ground	Required to ground	Required to ground
2) Grounding wire of the motor	Required to ground	Not required	Not required
3) Protective Earth Terminal of the motor	*	Not required	*

\* Ground if the grounding resistance of the standards that applies to the equipment is not satisfied.

### 1) Grounding the Protective Earth Terminal of the driver

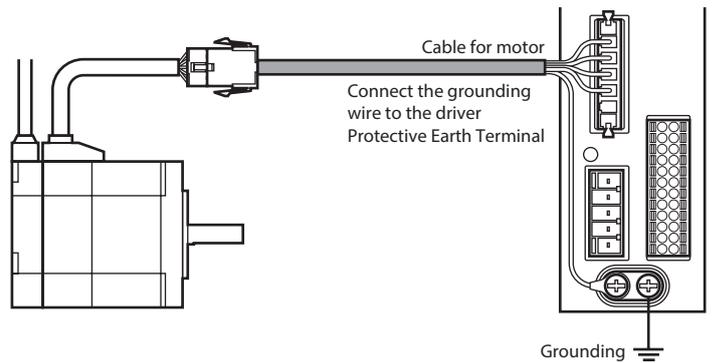
Connect the motor to the driver, and surely ground the Protective Earth Terminal of the driver. Refer to the [OPERATING MANUAL Driver](#) for how to ground.

The figure shows the DC power input type.



### 2) Grounding the grounding wire of the motor [AC power input type only]

Connect the grounding wire of the "cable for motor" to the driver Protective Earth Terminal.



### 3) Grounding the Protective Earth Terminal of the motor

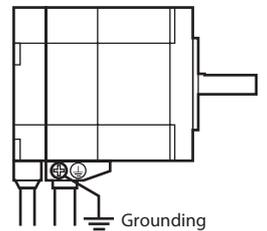
Be sure to ground the Protective Earth Terminal of the motor.

Grounding wire: AWG18 (0.75 mm<sup>2</sup>) or more  
 Screw size: M4

Tightening torque: 1.2 N·m (170 oz-in)

To ground the motor, use a round terminal, screw, and washer.

Ground wires and crimp terminals are not included.



## Inspection and maintenance

### Inspection

It is recommended that periodic inspections would be conducted for the items listed below after each operation of the motor. If an abnormal condition is noted, discontinue any use and contact your nearest Oriental Motor sales office.

#### During inspection

- Are any of the screws having installed the motor comes loose?
- Are there any abnormal noises in the motor bearings (ball bearings) or other moving parts?
- Are there any scratches, signs of stress or loose driver connection in the motor cable?
- Are the motor's output shaft and load shaft out of alignment?

### Warranty

Check on the Oriental Motor Website or General Catalog for the product warranty.

### Disposal

Dispose the product correctly in accordance with laws and regulations, or instructions of local governments.

## General specifications

Degree of protection	Excluding the mounting surface and connectors. IP40: <b>AZM14, AZM15, AZM24, AZM26, AZM46</b> (*1), <b>AZM48</b> (*1), <b>AZM66</b> (*1), <b>AZM69</b> (*1) IP66: Motors other than the above types	
Operation environment	Ambient temperature	0 to +40 °C (+32 to +104 °F) (non-freezing) *2
	Humidity	85% or less (non-condensing)
	Altitude	Up to 1,000 m (3,300 ft.) above sea level
	Surrounding atmosphere	No corrosive gas, dust, water or oil
Storage environment	Ambient temperature	-20 to +60 °C (-4 to +140 °F) (non-freezing)
	Humidity	85% or less (non-condensing)
Shipping environment	Altitude	Up to 3,000 m (10,000 ft.) above sea level
	Surrounding atmosphere	No corrosive gas, dust, water or oil
Insulation resistance	100 MΩ or more when 500 VDC megger is applied between the following places: • Case - Motor windings • Case - Electromagnetic brake windings	
Dielectric strength	Sufficient to withstand the following for 1 minute: • AC power input type • Case - Motor windings 1.5 kVAC 50/60 Hz • Case - Electromagnetic brake windings 1.5 kVAC 50/60 Hz • DC power input type • Case - Motor windings 1.0 kVAC 50/60 Hz *3 • Case - Electromagnetic brake windings 1.0 kVAC 50/60 Hz *3	

\*1 When the cable outlet direction is in the horizontal direction with respect to the motor.

\*2 Based on our measurement conditions.

\*3 0.5 kVAC 50/60 Hz for **AZM14, AZM15, AZM24**, and **AZM26**

## Regulations and standards

### ■ UL Standards

Check the "APPENDIX UL Standards for **AZ Series**" for recognition information about UL Standards.

### ■ CE Marking

Motors of AC power input type are affixed the CE Marking under the Low Voltage Directive.

### ● Low Voltage Directive

- This product cannot be used in IT power distribution systems.
- Install the product within the enclosure in order to avoid contact with hands.
- When a product can be touched with hands, be sure to ground. Make sure to ground the Protective Earth Terminals of the motor and driver.
- To protect against electric shock using an earth leakage breaker (RCD), connect a type B earth leakage breaker to the primary side of the driver.
- When using a circuit breaker (MCCB), use a unit conforming to the EN or IEC standard.
- Isolate the motor cable, power-supply cable and other drive cables from the signal cables by means of double insulation.
- The temperature of the driver's heat sink may exceed 90 °C (194 °F) depending on the driving conditions. Accordingly, take heed of the following items:
  - Do not touch the driver.
  - Do not use the driver near flammable objects.
  - Always conduct a trial operation to check the driver temperature.

### ● Applicable Standards

EN 60034-1, EN 60034-5, EN 60664-1

### ● Installation condition (EN Standards)

- To be incorporated in equipment
- Overvoltage category: II
- Pollution degree: 3
- Degree of protection: IP66
- Protection against electric shock: Class I

### ● EMC Directive

The **AZ Series** motor conforms to the EMC Directive in a state where the motor is connected with the driver. For details, refer to the [OPERATING MANUAL Driver](#).

### ■ RoHS Directive

The products do not contain the substances exceeding the restriction values of RoHS Directive (2011/65/EU).



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ORIENTAL MOTOR U.S.A. CORP.  
 Technical Support Tel:(800)468-3982  
 8:30 A.M. to 5:00 P.M., P.S.T. (M-F)  
 7:30 A.M. to 5:00 P.M., C.S.T. (M-F)  
[www.orientalmotor.com](http://www.orientalmotor.com)

ORIENTAL MOTOR DO BRASIL LTDA.  
 Tel:+55-11-3266-6018  
[www.orientalmotor.com.br](http://www.orientalmotor.com.br)

ORIENTAL MOTOR (EUROPA) GmbH  
 Schiessstraße 44, 40549 Düsseldorf, Germany  
 Technical Support Tel:00 800/22 55 66 22  
[www.orientalmotor.de](http://www.orientalmotor.de)

ORIENTAL MOTOR (UK) LTD.  
 Tel:01256-347090  
[www.oriental-motor.co.uk](http://www.oriental-motor.co.uk)

ORIENTAL MOTOR (FRANCE) SARL  
 Tel:01 47 86 97 50  
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ORIENTAL MOTOR ITALIA s.r.l.  
 Tel:02-93906346  
[www.orientalmotor.it](http://www.orientalmotor.it)

ORIENTAL MOTOR CO., LTD.  
 4-8-1 Higashiueno, Taito-ku, Tokyo 110-8536  
 Japan  
 Tel:03-6744-0361  
[www.orientalmotor.co.jp](http://www.orientalmotor.co.jp)

ORIENTAL MOTOR ASIA PACIFIC PTE. LTD.  
 Singapore  
 Tel:1800-8420280  
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 Tel:1800-888-881  
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[www.orientalmotor.com.tw](http://www.orientalmotor.com.tw)

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 Tel:400-820-6516  
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 Korea  
 Tel:080-777-2042  
[www.inaom.co.kr](http://www.inaom.co.kr)

ORIENTAL MOTOR CO., LTD.  
 Hong Kong Branch  
 Tel:+852-2427-9800