

Small Robots OVR

5-axis Vertically Articulated OVR5035K1-V

Technical Reference



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Thank you for purchasing an Oriental Motor product.
This document describes product handling procedures and safety precautions.

- Please read it thoroughly to ensure safe operation.
- Always keep the document where it is readily available.

1 Introduction

1-1 Before use

Only qualified personnel of electrical and mechanical engineering should work with the product. Use the product correctly after thoroughly reading the "2 Safety precautions" on p.3. In addition, be sure to observe the contents described in warning, caution, and note in this document. The product described in this document is designed and manufactured to be incorporated in general industrial equipment. Do not use for any other purpose. Oriental Motor Co., Ltd. is not responsible for any compensation for damage caused through failure to observe this warning.





2 Safety precautions

The precautions described below are intended to ensure the safe and correct use of the product, and to prevent the customer and others from exposure to the risk of injury. Use the product only after carefully reading and fully understanding these instructions.

In regard to a robot, it is prohibited to start operating the robot (i.e., to operate the device in accordance with the specified purpose) when the machine in which the robot is incorporated does not satisfy any relevant safety standards.

The factory safety manager or safety personnel in charge of the applicable machine must ensure that the machine is operated only by qualified personnel who are familiar with the operation of electronic equipment, and thereby prevent injury or damage to the equipment.

The term "qualified personnel" refers to persons who have received the necessary training or education and have pertinent experience; who are familiar with the relevant standards, regulations, accident-prevention rules and inspection conditions; who are authorized by the factory safety manager to engage in the necessary activities; and who have the ability to discern and prevent potential dangers.

| | |
|--|---|
|  WARNING | Handling the product without observing the instructions that accompany a "WARNING" symbol may result in death or serious bodily injury. |
|  CAUTION | Handling the product without observing the instructions that accompany a "CAUTION" symbol may result in bodily injury or property damage. |
|  Note | The items under this heading contain important handling instructions that the user should observe to ensure the safe use of the product. |
|  memo | The items under this heading contain related information and contents to gain a further understanding of the text in this document. |

WARNING

General

- Never use the product for equipment in connection with the maintenance or management of human life or health.
- Do not use the product in explosive or corrosive environments, in the presence of flammable gases, in areas subjected to splashing water, or near combustible materials. Doing so may result in fire or injury.
- Assign qualified personnel having expert knowledge on electrical and mechanical engineering as well as safety to the task of installing, wiring, operating/controlling, inspecting and troubleshooting the product. Handling by unqualified personnel may result in fire, injury, or damage to equipment.
- Conduct a risk assessment in a state where all parts and components including the product have been installed in the equipment. Failure to do so may result in injury or damage to equipment.
- Provide a safety cage that meets the safety distance specified in ISO 13857 so that an operator or other personnel does not enter the movable range of the product while the equipment is operating. Failure to do so may result in injury.
- When teaching, adjusting, or inspecting the product inside the safety cage, take appropriate safety measures according to the results of the risk assessment of the entire equipment. Failure to do so may result in injury.
- Provide appropriate safety measures so that the entire equipment will operate safely in the event of a system failure or malfunction. Failure to do so may result in injury.
- Provide an emergency stop function for the equipment. Failure to do so may result in injury.
- The function and performance of the safety-related control system are appropriately determined according to the results of the risk assessment of the entire equipment. This may result in injury.
- Do not disassemble any components other than those specified for the motor replacement work. Also, do not modify the product. Doing so may result in injury or damage to equipment.
- Use the product in a condition where the entire equipment complies with relevant international standards such as ISO 12100, ISO 10218-1, ISO 10218-2, national standards, and legal regulations such as occupational health and safety required in each country. Failure to do so may result in injury or damage to equipment.
- Do not install, connect, or inspect/troubleshoot the product while the power is on. When working with the power on state, provide work rules in accordance with the Ordinance on Industrial Safety and Health and take appropriate safety measures. Failure to do so may result in fire, injury, or damage to equipment.
- Do not allow your hands to be caught in moving parts of the product. Doing so may result in injury or damage to equipment.

Installation and wiring

- Since the product is very heavy, make sure that two or more people work together to perform the necessary tasks when transporting or installing it. This may result in injury.
- Wear a helmet, safety shoes, gloves, or other protective equipment when transporting or installing the product. Failure to do so may result in injury.
- Be sure to secure the product itself according to the instructions. Failure to do so may result in injury or damage to equipment.
- Be sure to wire and connect according to the instructions. Failure to do so may result in fire or damage to equipment.
- Install an external fuse, if necessary, to prevent ignition due to a large amount of current flowing from the power supply side.
- Do not pull or forcibly bend the arm section or cable. Also, do not lift the product by holding the cable. Doing so may result in injury or damage to equipment.

Warning for transportation of heavy load

- Make sure that two or more people work together to perform the necessary tasks or that a crane is used when transporting the product.
- When working with two or more people, clarify the relationship and roles of the primary worker and assistant worker, and transport the product while communicating with each other to ensure safety.
- When using a crane, do not suspend a load exceeding the rated load of the crane.
- Consider the cutting load and safety factor of the lifting tool and select one that is suitable for transporting the product. Also, make sure that the lifting tool is not damaged.
- Do not ride on a load suspended by the crane.
- Do not leave the crane in a state where the load is suspended.
- Do not stand under the crane where the load is suspended.

Operation

- Before operating a robot, check the condition of the surrounding area to ensure safety. This may cause injury or damage to equipment.
- Take appropriate safety measures when placing the motor in a non-excitation state. Failure to do so may result in injury or damage to equipment.
- Do not turn off the power or input a signal to place the motor in a non-excitation state during operation. The robot may move unexpectedly, causing injury or damage to equipment.
- When turning on the driver power, make sure there is no signal input from the host controller. The product may start operating unintentionally, causing injury or damage to equipment.
- When operating the product after the driver power supply is turned on or the power to the motor is turned off, adjust the position at low speed to ensure safety. Failure to do so may result in injury or damage to equipment.
- Turn off the power supply of the driver in the event of a power failure. Otherwise, the product may start suddenly when the power is restored, causing injury or damage to equipment.
- If an abnormality occurs in the product, immediately stop operation and turn off the power to the motor that drives the product. Failure to do so may result in injury or damage to equipment.

Maintenance and inspection

- Perform the pre-work (daily) inspection and periodic inspection according to the instructions in this manual, and check that there are no abnormalities in the product and related equipment before working. Failure to do so may result in injury or damage to equipment.
- If it is necessary to replace the motor for maintenance, contact your nearest sales office.

CAUTION

- Do not use the product beyond its specifications. Doing so may result in injury or damage to equipment.
- Keep the area around the product free of combustible materials. Failure to do so may result in fire or a skin burn(s).
- Do not leave anything around the product that would obstruct ventilation. Doing so may result in damage to equipment.
- Use a driver and cable that are connected to the motor only in the specified combination. Failure to do so may result in fire, injury, or damage to equipment.
- When conducting the insulation resistance measurement or the dielectric strength test, be sure to separate the connection between the product and the driver. Failure to do so may result in damage to equipment.
- Take measures against static electricity when handling. Static electricity may cause the encoder (ABZO sensor) of the motor that drives the product or the driver to malfunction or be damaged.
- This may result in injury or damage to equipment.
- Keep the encoder (ABZO sensor) of the motor away from a strong magnetic field. This may damage to the encoder (ABZO sensor) or cause the product to malfunction. Injury or damage to equipment may result.
- Stop operation if abnormal noise or vibration occurs during operation. Failure to do so may result in injury or damage to equipment.

- Since the motor surface temperature may exceed 70 °C (158 °F) even under normal operating conditions, if the operator is allowed to approach the motor, affix a warning label shown in the figure on a conspicuous place. The surface is hot, and this may cause a skin burn(s).
- To protect the encoder (ABZO sensor), use the motor in a condition where the motor surface temperature does not exceed 80 °C (176 °F). Failure to do so may result in damage to equipment.
- Make sure not to apply a strong shock to the encoder (ABZO sensor) of the motor. This may damage to the encoder (ABZO sensor) and cause the product to malfunction, resulting in damage to the equipment. The label shown in the figure is affixed on the motor.
- Be careful not to make any mistakes in the combinations when connecting a motor and a driver. Wiring in the wrong combination may cause unexpected movement. This may result in injury or damage to equipment.
- When installing and wiring, take measures against EMC. Without effective measures to suppress Electromagnetic Interference (EMI) caused by the product or driver to the surrounding control system equipment and Electromagnetic Susceptibility (EMS) generated by the product or driver, the function of your equipment may be seriously affected. Verify EMC compliance with the completed equipment. This may result in injury or damage to equipment.
- The status of the actuating controls shall be clearly indicated, e.g. power on, fault detected, automatic operation. If an indicator light is used, it shall be suitable for its installed location and its color shall meet the requirement of IEC 60204-1.
- Since the Bp-axis (M4: wrist bending) of the product is not equipped with an electromagnetic brake, the arm tip may fall due to its own weight in the event of a power failure, emergency stop, or when the safety cage is opened. Take appropriate measures. This may result in damage to equipment.
- Be careful not to get your fingers caught in the stoppers that limit the movement of the L-axis (M2: lower arm) and U-axis (M3: upper arm) of the product. This may result in injury. The label shown in the figure is affixed on the stopper part.



Warning label



Warning label



Warning label

3 Preparation

3-1 Checking the product

Verify that the items listed below are included. Report any missing or damaged items to the Oriental Motor sales office from which you purchased the product.

- Robot 1 unit
- Positioning pin 1 pc.
- Unpacking instructions..... 1 copy

3-2 How to identify the product model

Check the model against the model shown on the nameplate.

OVR **5** **035** **K** **1** - **V**
 1 2 3 4 5

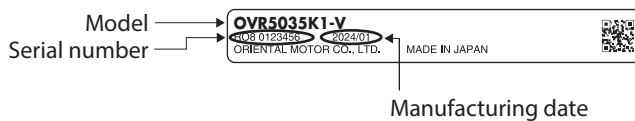
| | | |
|---|--------------------|-----------------------------------|
| 1 | Number of axes | 5 : 5-axis |
| 2 | Reach length | 035 : 350 mm (13.78 in.) |
| 3 | Power supply input | K : 24 VDC |
| 4 | Payload | 1 : 1 kg (2.2 lb.) |
| 5 | Robot type | V : Vertically articulated |

3-3 Products that can be combined

| Series | Driver type | Model |
|------------------|---------------------------------------|-----------------|
| AZ Series | Built-in controller type | AZD-KD |
| | mini Driver RS-485 communication type | AZD-KR2D |

3-4 Information about nameplate

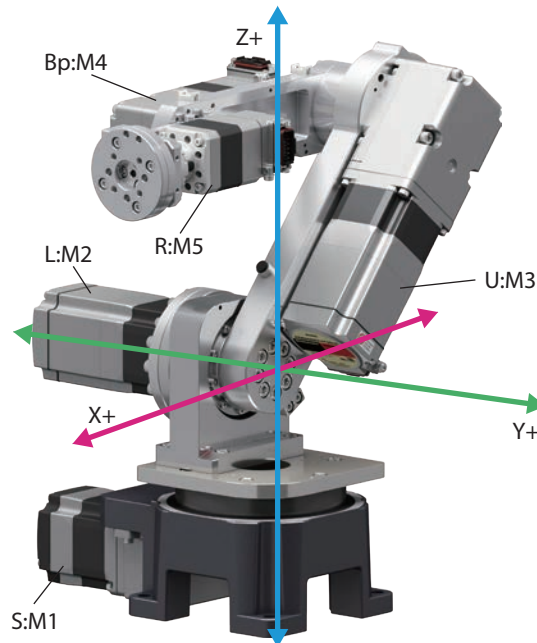
The figure shows an example.



3-5 Names of parts

The robot consists of five axes: S-axis (M1: rotation), L-axis (M2: lower arm), U-axis (M3: upper arm), Bp-axis (M4: wrist bending), and R-axis (M5: wrist rotation). All motors are of the **AZ** Series equipped with a battery-free absolute encoder (ABZO sensor).

The motors that drive the L-axis (M2: lower arm) and U-axis (M3: upper arm) are equipped with a power-off activated type electromagnetic brake.

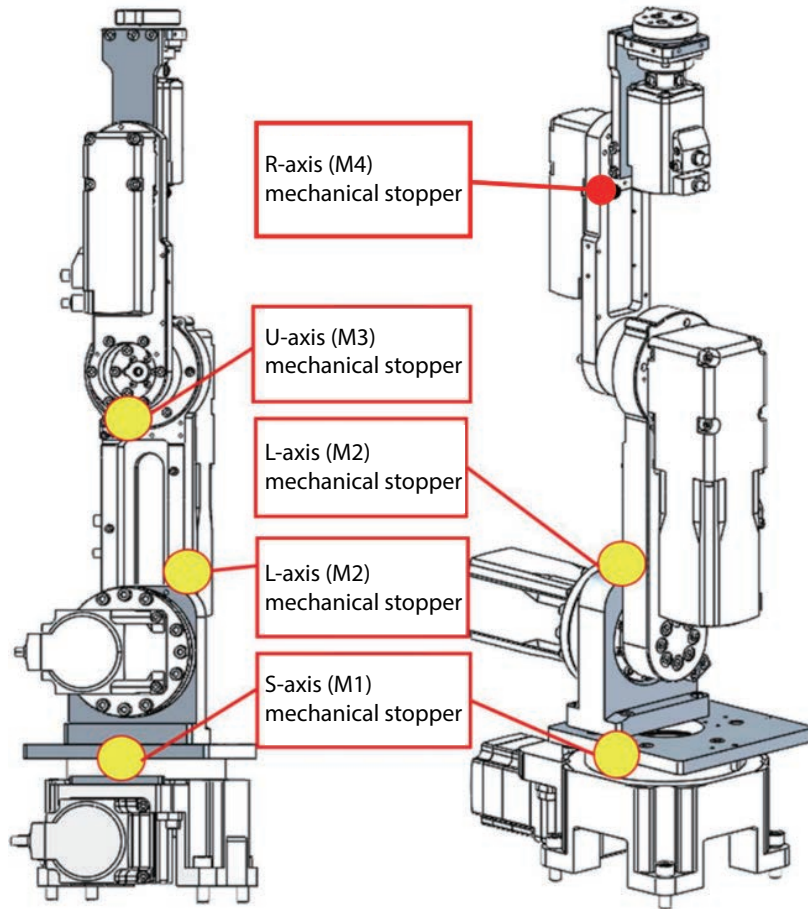


| Axis | Axis name | Model |
|---------|-----------|---|
| S-axis | M1 | DGB130R36-AZAKHL* |
| L-axis | M2 | AZM66MKH-CSG20-100 |
| U-axis | M3 | AZM66MKH-FC30UA |
| Bp-axis | M4 | AZM46AKH-FC30DA |
| R-axis | M5 | AZM46AKH, HPG-11B-09-F0CCC (Harmonic Drive Systems Inc.) |

* Contact your nearest Oriental Motor sales office to purchase the product.

3-6 Rotation limit mechanical stopper

This product is equipped with mechanical stoppers that limit the movable range.
The mechanical stopper of the S-axis (M1: rotation) can be changed the position at 90° intervals.



Note The rotation limit mechanical stoppers are not intended to protect the axis (axes) from falling. Check to ensure safety to use.

4 Installation of robot

4-1 Installation location

The product is designed and manufactured to be incorporated in general industrial equipment. Install it in a well-ventilated location that provides easy access for inspection. The location must also satisfy the following conditions:

- Inside an enclosure that is installed indoors (provide vent holes)
- Operating ambient temperature: 0 to +40 °C [+32 to +104 °F] (non-freezing)
- Operating ambient humidity: 85 % or less (non-condensing)
- Area free of explosive atmosphere, toxic gas (such as sulfuric gas), or liquid
- Area not exposed to direct sun
- Area free of excessive amount of dust, iron particles or the like
- Area not subject to splashing water (rain, water droplets), oil (oil droplets) or other liquids
- Area free of excessive salt
- Area not subject to continuous vibration or excessive shocks
- Area free of excessive electromagnetic noise (from welders, power machinery, etc.)
- Area free of radioactive materials, magnetic fields or vacuum
- Up to 1,000 m (3,300 ft.) above sea level

4-2 Unpacking method



- Wear protective equipment (helmet, safety shoes, gloves) when working.
- Since the motor is very heavy, make sure that two or more people work together to perform the necessary tasks when transporting or installing it.

1. Place the package on a horizontal, flat surface to unpack. The product is not in a fixed state in the package. Be careful when handling the product as it may tilt.
2. Hold the gear and actuator sections of the L-axis (M2) with both hands and take out the product. When removing, be sure to use both hands to hold the specified positions. Improper holding, such as holding the product with one hand or in a position other than that specified, may cause the axis to move in an unexpected direction, resulting in a fall or injury.



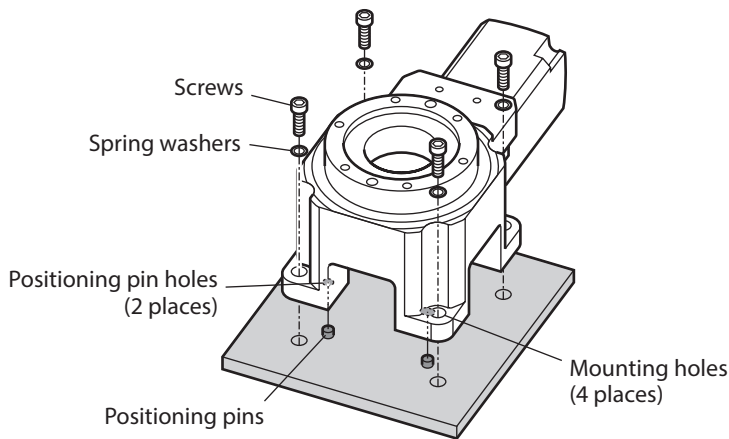
3. Place the product in the installation place and remove the packing materials.

4-3 Installation method

- Note**
- Ensure that there is sufficient work space at the installation site so that teaching and maintenance/ inspection can be performed safely.
 - Do not loosen or remove any screws on the product. This may result in reduced positioning accuracy or damage to the product.
 - Work in a stable condition so that the product does not tilt.
 - Install the product on a metal surface of sufficient strength to prevent vibration or twisting of an enclosure in which the product is installed.

Use four mounting holes of the S-axis (M1: rotation) to secure the product to the mounting plate. Provide screw holes in the mounting plate.

When positioning the product, use two positioning pin holes.



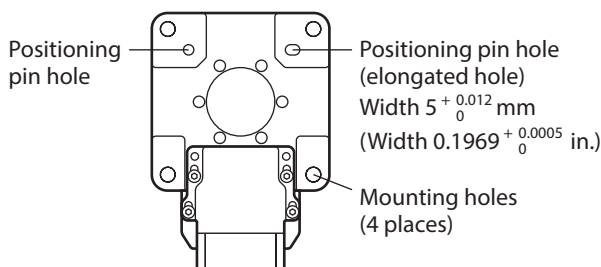
- Note** Be sure to install the product from the top of the mounting plate. It cannot be installed from the bottom.

Screws, spring washers, positioning pins are to be provided by the customer.

The values of the tightening torque are recommended. Tighten the screws to an appropriate torque according to the design conditions of the mounting plate.

| | | |
|-----------------------|-------------------|---|
| Mounting plate | Thickness | 10 mm (0.39 in.) or more |
| | Material | Steel |
| Mounting holes | Hole diameter | ø9 mm (ø0.35 in.) |
| | Nominal size | M8 |
| | Tightening torque | 13 N·m (115 lb-in) |
| Positioning pin holes | Pin hole diameter | $\phi 5^{+0.012}_0$ mm ($\phi 0.1969^{+0.0005}_0$ in.) |
| | Pin hole depth | 5 mm (0.20 in.), blind hole |

Figure viewed from the installation surface side



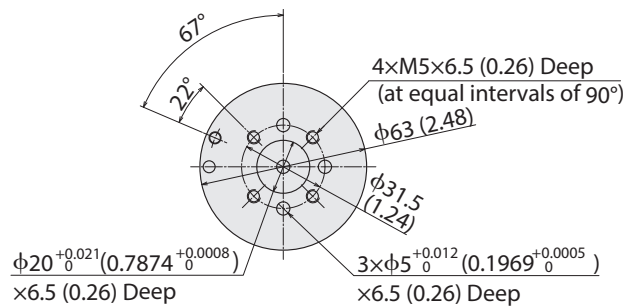
4-4 Installation of the end effector

Use four end effector mounting holes of the R-axis (M5: wrist rotation) to install the end effector with screws. Use three positioning pin holes of the R-axis (M5: wrist rotation) when positioning the end effector. The values of the tightening torque are recommended. Tighten the screws to an appropriate torque according to the design conditions of the end effector.

| | | |
|----------------------|---------------------------------|---|
| End effector | Material | Steel or aluminum |
| Mounting hole | Nominal size | M5 |
| | Tightening torque | 5 N·m (710 oz-in) |
| | Effective depth of screw thread | 6.5 mm (0.26 in.) |
| Positioning pin hole | Pin hole diameter | $\phi 5 \begin{smallmatrix} +0.012 \\ 0 \end{smallmatrix}$ mm ($\phi 0.1969 \begin{smallmatrix} +0.0005 \\ 0 \end{smallmatrix}$ in.) |
| | Pin hole depth | 6.5 mm (0.26 in.), blind hole |

Mounting face of R-axis (M5: wrist rotation) [Unit: mm (in.)]

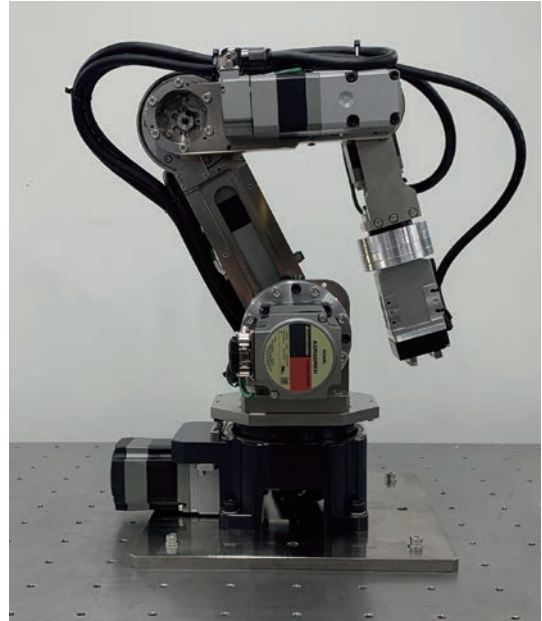
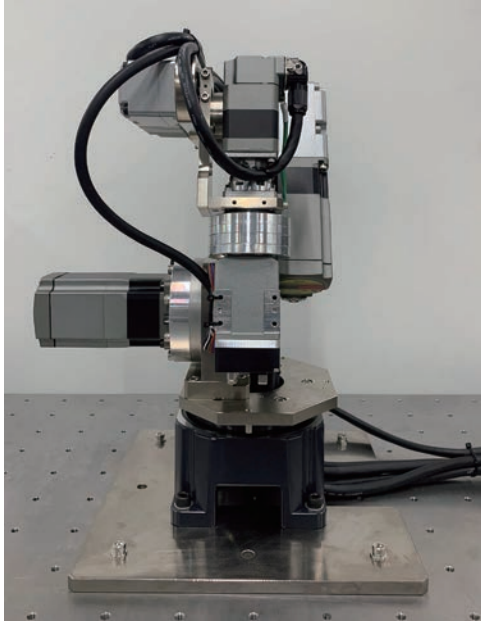
Compliant with ISO 9409-1-31.5-4-M5



4-5 Wiring example

The figure shows a reference picture.

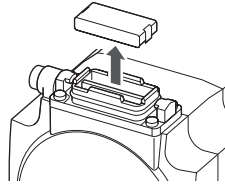
- Fix the cable at the positions near the connectors so that the connectors do not move.
- Make sure to wire the cable providing a looseness so that no stress is applied to it.
- Maintain 10 m (32.8 ft.) or less for the total wiring distance of the cable.



4-6 Connection of the motor

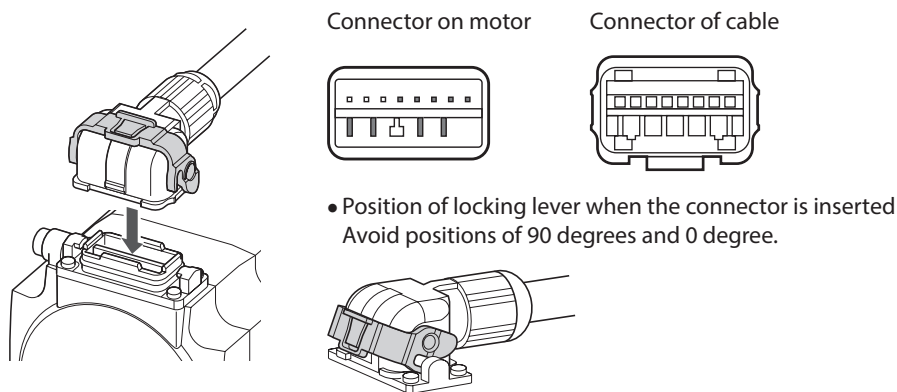
Please check the connection method below.

1. Remove the connector cap.

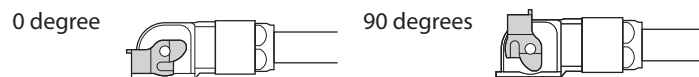


Note Do not damage the O-ring of the connector when removing the connector cap.

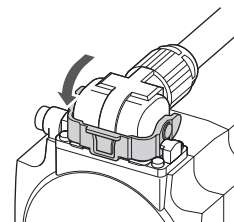
2. Connect the connector of the connection cable. The figure shows an example using the connection cable of cable outlet in output shaft direction. Check the terminal position of the connector before connecting.



Note If the locking lever is in a state of being turned up to the 90-degree position or down to the 0-degree position, parts around the locking lever and the connector contact with each other, and the connector cannot be connected.



3. Turn down the locking lever to the 0-degree position to fix the connector.



Handling of locking lever

- Do not apply a strong force to the locking lever. If the locking lever is damaged, the connector may not be fixed securely.
- After connecting the connector, securely turn down the locking lever to the 0-degree position to fix the connector.

! WARNING Be sure to turn down the locking lever. If the connector is not fixed, the cable may come off, resulting in fire, electrical shock, or damage to equipment.

Detaching the cable

Turn up the locking lever and pull out the connector.

memo Turning up the locking lever to the 90-degree position will detach the connector at the same.

5 Setup

5-1 Setup method

Set the information of the robot with the **MRC Studio** programming software.

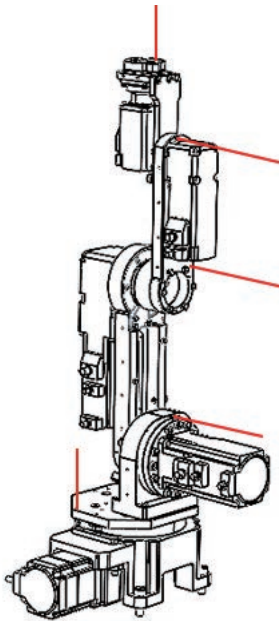
1. Start the **MRC Studio** software.
2. Click [Communication port], select a connected controller.
3. Click [Setup] on the start screen.
4. Set the robot type and the mechanism information according to the instructions on the screen.

5-2 Origin posture at setup

This product provides five positioning pin holes for origin setting. The position where the included positioning pin can be inserted will be the origin of the axis.

Move the axis to a position where the positioning pin for origin setting can be inserted and set the origin of the axis.

Pin Hole Diameter: $\varnothing 4 \begin{smallmatrix} +0.012 \\ 0 \end{smallmatrix}$ mm ($\varnothing 0.1575 \begin{smallmatrix} +0.0005 \\ 0 \end{smallmatrix}$ in.)



The origin setting is not required when using the MRC01 robot controller or the **MRCU** Series integrated robot controller & drivers. Set the origin of the replaced axis only when the motor is replaced.

6 Maintenance

Daily and periodic inspections should be carried out by workers with sufficient knowledge and experience in accordance with “2 Safety precautions” on p.3. Be sure to perform these inspections to prevent malfunctions and ensure safety, and confirm that there are no abnormalities in the product and related equipment before starting work. If you find any abnormality, please stop using it immediately and take any necessary repairs or other measures.

6-1 Inspection

■ Inspection interval

If the robot is operated eight hours a day, perform maintenance according to the applicable period specified in the table. Reduce maintenance intervals accordingly if the operating rate is high such as continuous operation for twenty-four hours.

| Maintenance timing | Inspection | Cleaning |
|------------------------------------|------------|----------|
| When operated for the first time | ○ | — |
| Six months after initial operation | ○ | — |
| Every six months thereafter | ○ | — |
| As needed | — | ○ |

■ Inspection item

- Check to see if the position securing the product is loose.
- Check to see if any of the screws securing the end effector are loose.
- Check to see if the cable is damaged, scraped or stressed.
- Check to see if the connection between the motor and driver is loose.
- Before and after the power is turned on, check to see if there is any abnormal noise or vibration coming from the bearing or gears.
- Check to see if the operating point has shifted during return-to-home operation and normal operation (original program operation).



- When carrying out each inspection, please record the inspection results and special notes on the daily inspection sheet.
- Perform inspections outside the moving range as much as possible.
- When repairs are performed during inspection, please record the details and save it for at least 3 years.



Replace the cable if it is worn out as a result of inspection.

■ Cleaning

- Wipe off any dirt and stains using a soft cloth. To remove stubborn stains, wipe the area using a soft cloth moistened with neutral detergent.
- Do not apply compressed air. Dust may enter through gaps.
- Do not use petroleum solvents, since they will damage the coated surface.

6-2 Warranty

Check on the Oriental Motor Website for the product warranty.

6-3 Disposal

Dispose the product correctly in accordance with laws and regulations, or instructions of local governments.

7 Specifications

7-1 Product specifications

Check on the Oriental Motor Website for the product specifications.

7-2 General specifications

| | | |
|-----------------------|------------------------|--|
| Degree of protection | | IP40 (Excluding connector part) |
| Operating environment | Ambient temperature | 0 to +40 °C [+32 to +104 °F] (non-freezing) |
| | Humidity | 85 % or less (non-condensing) |
| | Altitude | Up to 1,000 m (3,300 ft.) above sea level |
| | Surrounding atmosphere | No corrosive gas, dust, water or oil |
| Storage environment | Ambient temperature | -20 to +60 °C [-4 to +140 °F] (non-freezing) |
| | Humidity | 85 % or less (non-condensing) |
| Shipping environment | Altitude | Up to 3,000 m (10,000 ft.) above sea level |
| | Surrounding atmosphere | No corrosive gas, dust, water or oil |

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